



Validation Of A Buoyancy-Modified Turbulence Model By Numerical Simulations Of Breaking Waves Over A Fixed Bar

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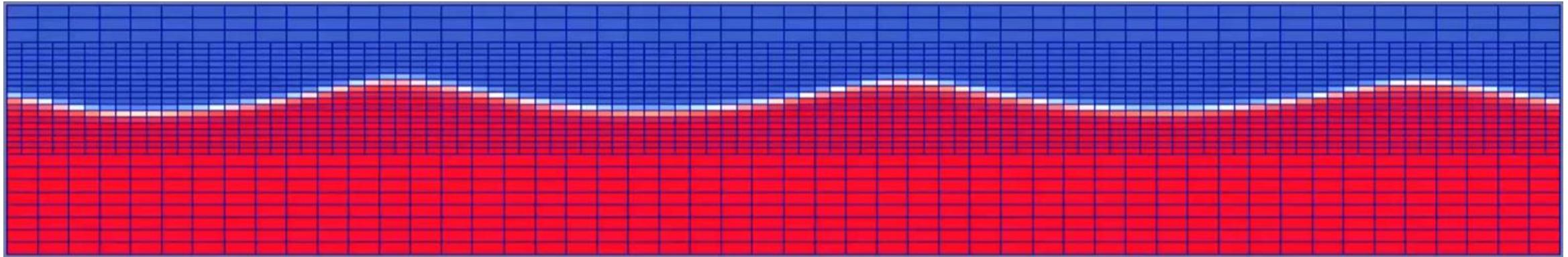
Overview

- CFD numerical wave tank
- RANS turbulence modelling
 - Wave propagation
 - Wave breaking
- Breaking waves over a fixed bar
- Conclusions

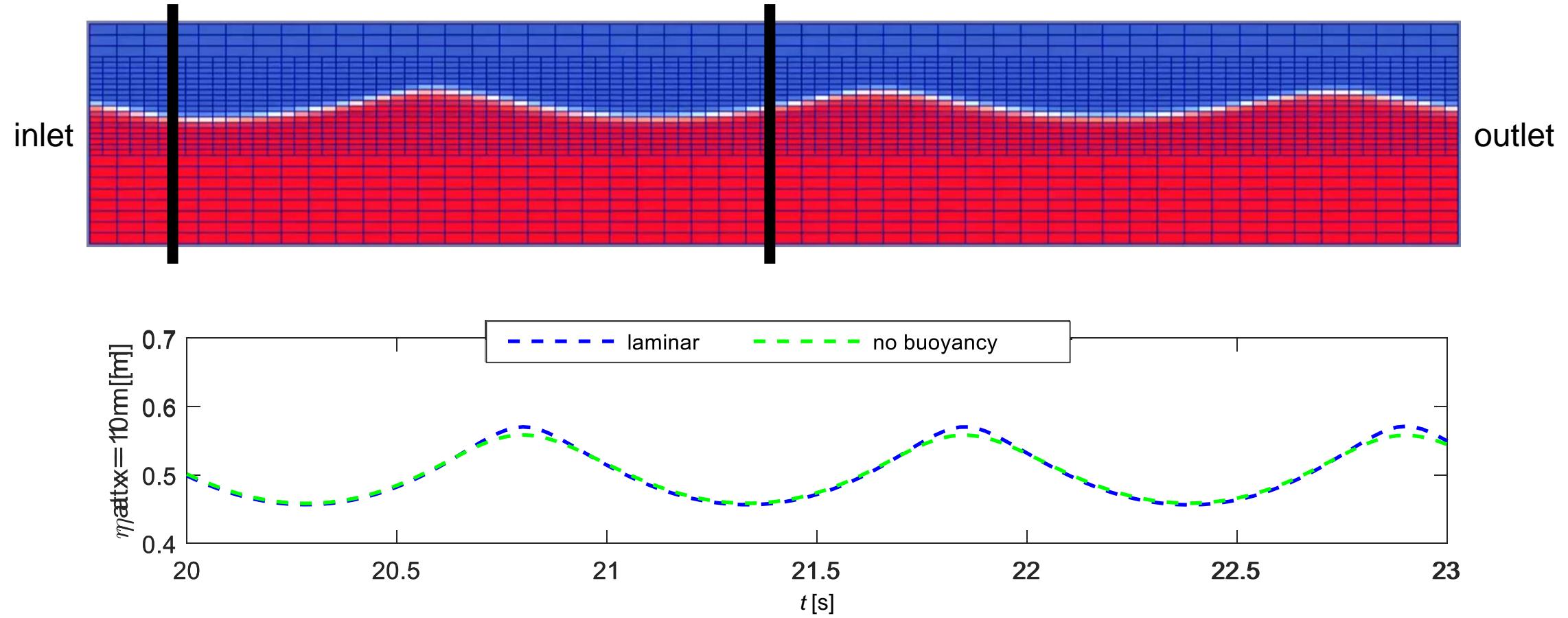


CFD numerical wave tank

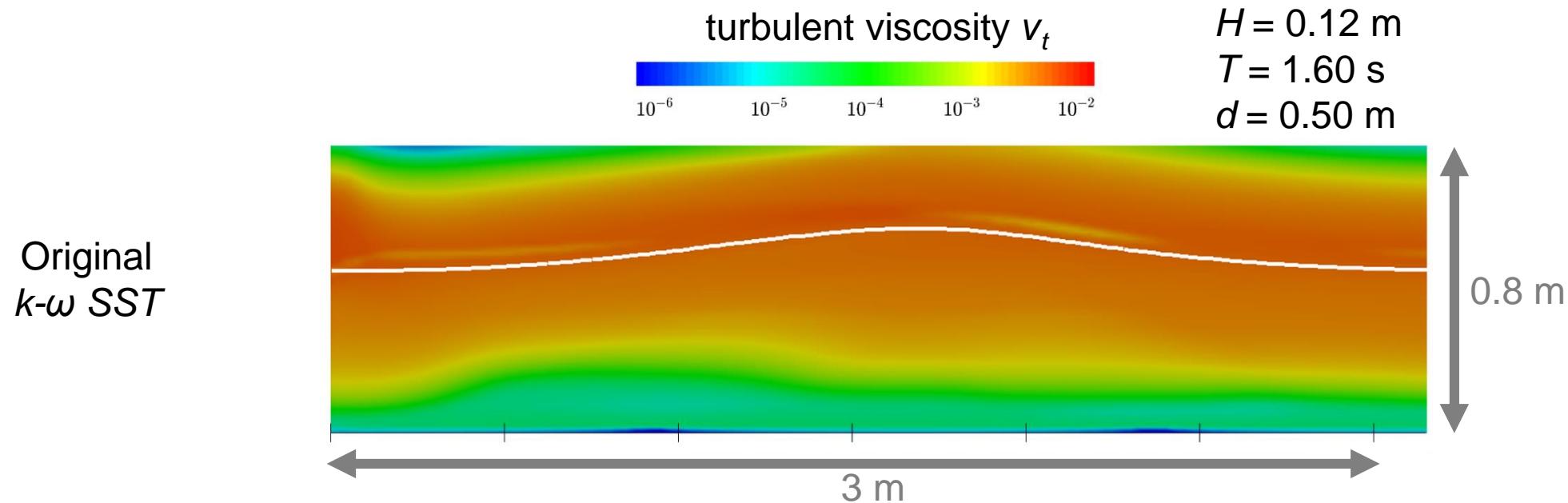
- Non-linear viscous numerical wave tank in OpenFOAM
 - = box filled with water (red) and air (blue)
 - p and U : Navier-Stokes equations
 - volume fraction α : Volume of Fluid (VoF) method
- Boundary conditions for wave generation and wave absorption



Wave damping due to RANS turbulence modelling



Wave damping due to RANS turbulence modelling



$$\frac{\partial k}{\partial t} + \frac{\partial u_j k}{\partial x_j} - \frac{\partial}{\partial x_j} \left[(\nu + \sigma_k v_t) \frac{\partial k}{\partial x_j} \right] = P_k - \beta^* \omega k$$

$$P_k = \min \left(v_t \frac{\partial u_i}{\partial x_j} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right), 10 \beta^* k \omega \right)$$

$$\frac{\partial \omega}{\partial t} + \frac{\partial u_j \omega}{\partial x_j} - \frac{\partial}{\partial x_j} \left[(\nu + \sigma_\omega v_t) \frac{\partial \omega}{\partial x_j} \right] = \frac{\gamma}{\nu_t} G - \beta \omega^2 + 2(1 - F_1) \frac{\sigma_{\omega 2}}{\omega} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}$$

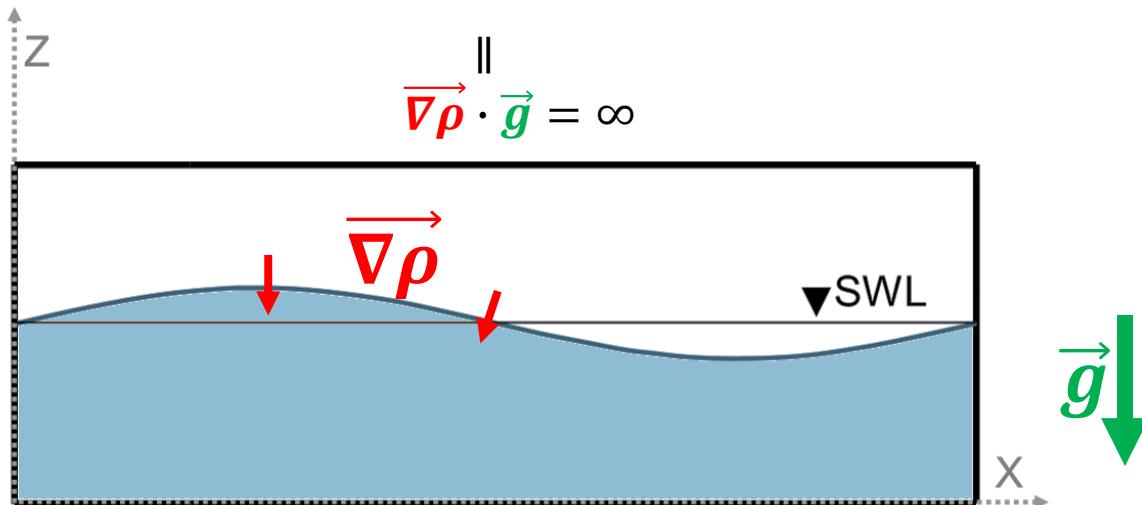
$$v_t = \frac{a_1 k}{\max(a_1 \omega, SF_2)}$$

Buoyancy-modified turbulence model

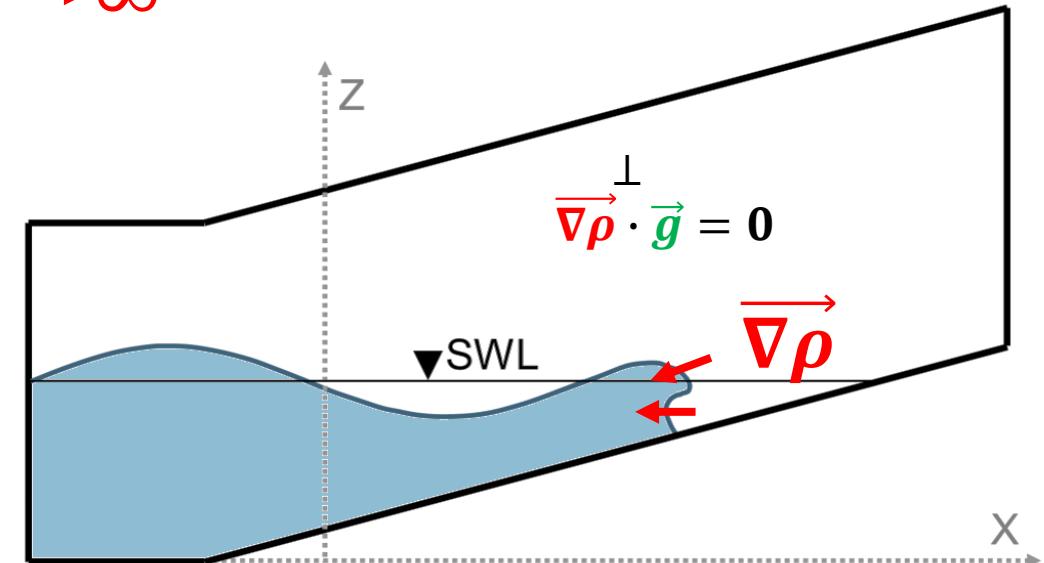
- Density included in the k -equation and ω -equation for $k-\omega$ and $k-\omega$ SST
- Buoyancy source term G_b in the k -equation (implicitly implemented):

$$G_b = -\frac{v_t}{\sigma_t} \nabla \rho \cdot \vec{g}$$

$\hookleftarrow \infty$

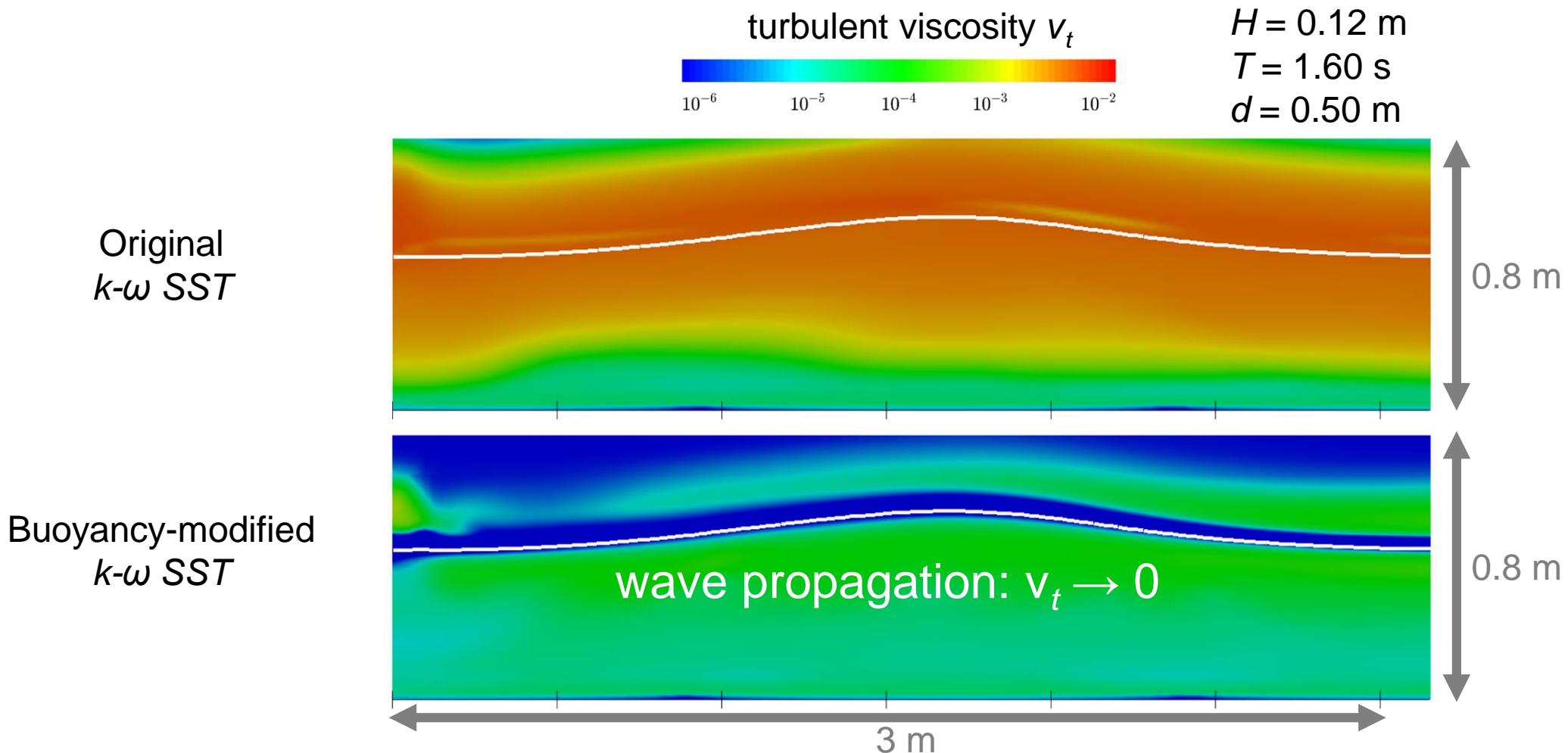


wave propagation: $v_t \rightarrow 0$

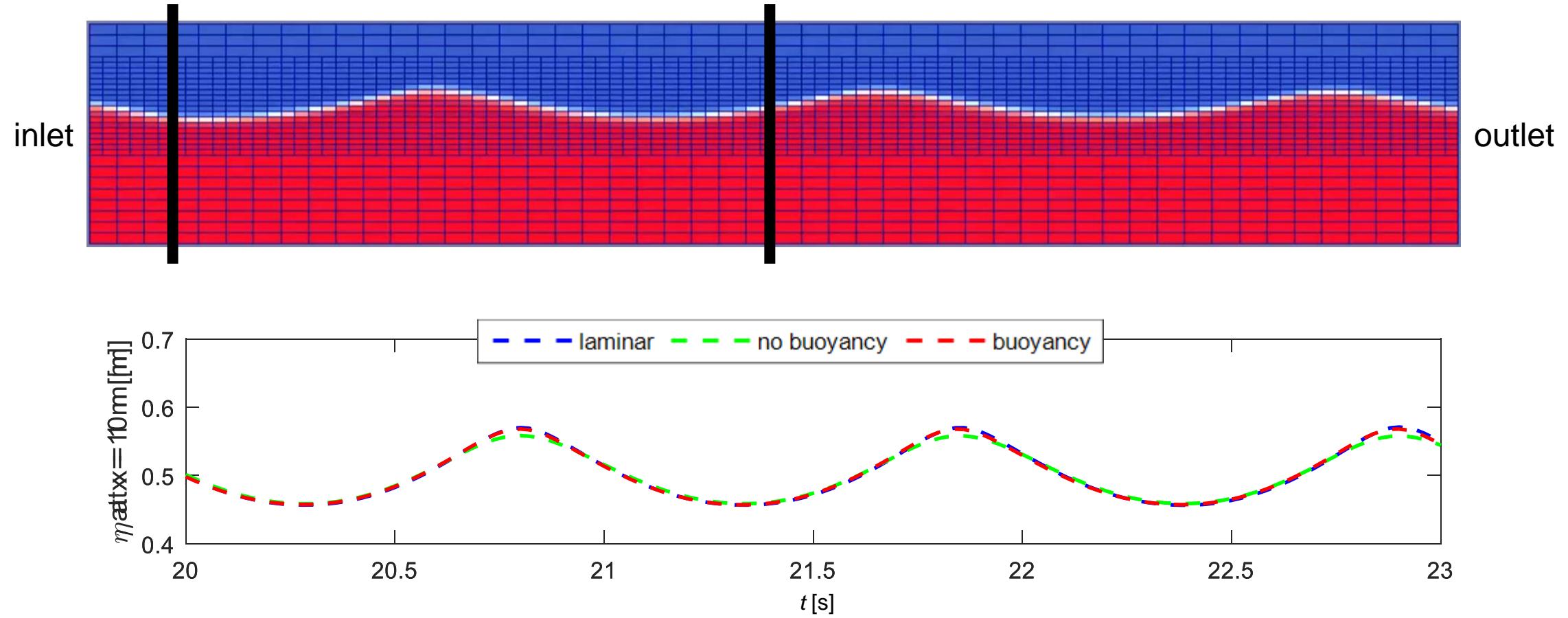


wave breaking : $G_b \rightarrow 0$

Wave damping due to RANS turbulence modelling

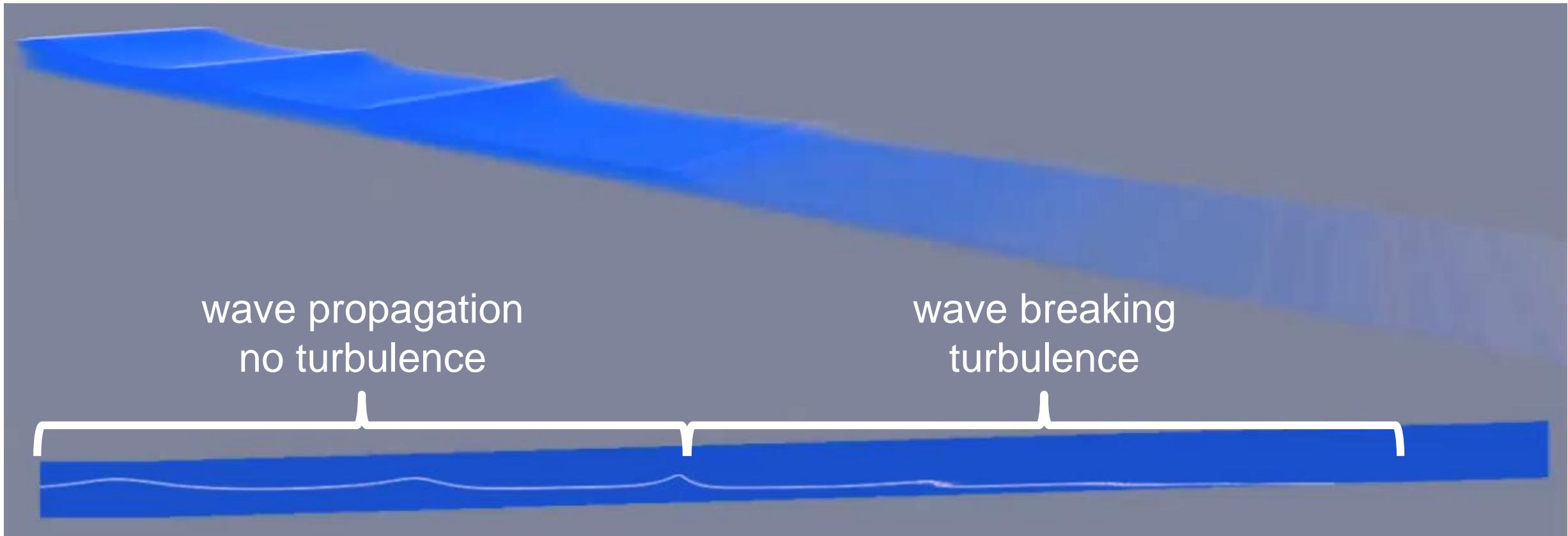


Wave damping due to RANS turbulence modelling



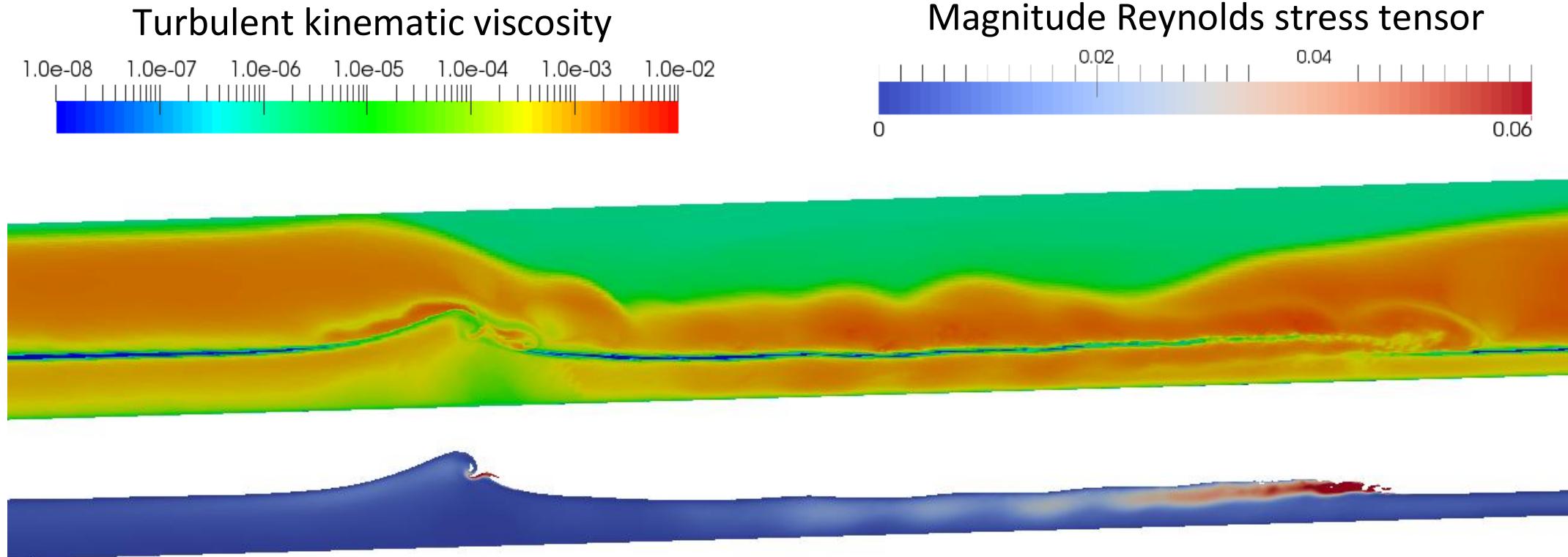
Wave breaking (spilling)

Experiments: F.C.K. Ting, J.T. Kirby, Observation of undertow and turbulence in a laboratory surf zone, Coastal Engineering 24 (1994) 51–80.



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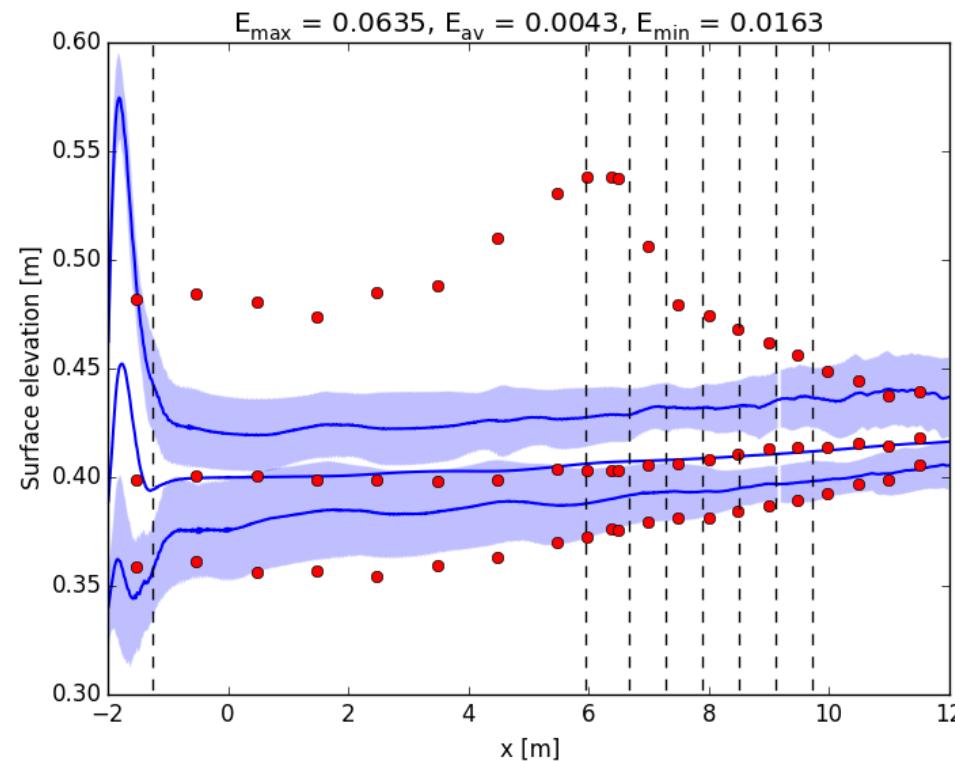


wave breaking : $G_b \rightarrow 0$

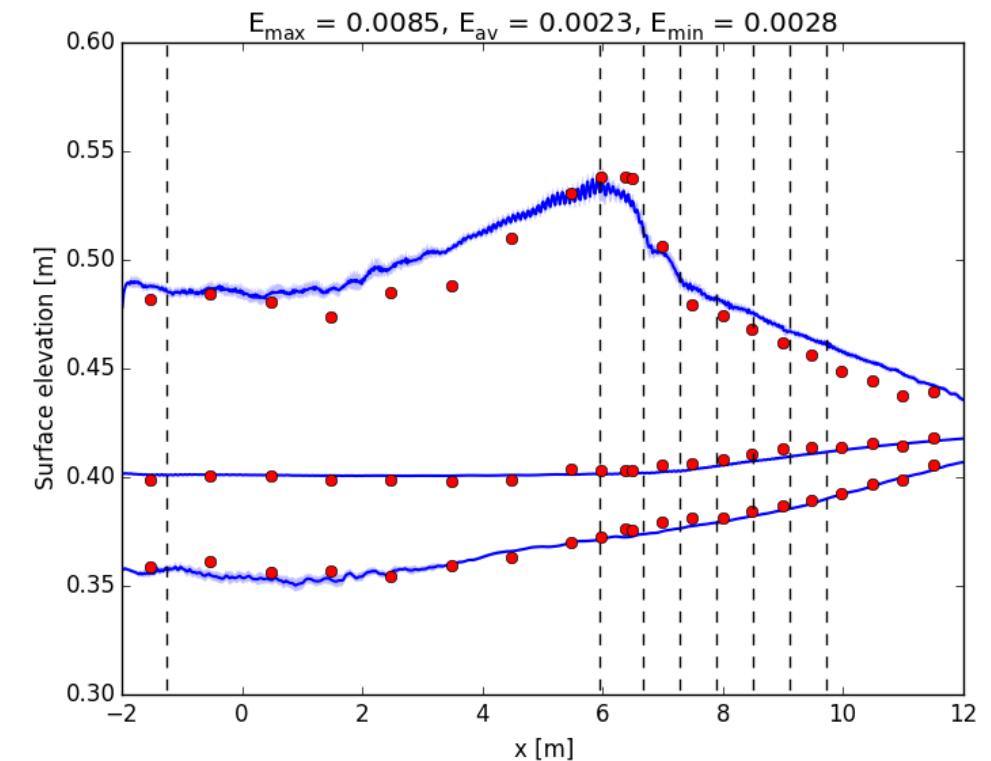
Wave breaking (spilling)

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original $k-\omega$ model



buoyancy-modified $k-\omega$ model

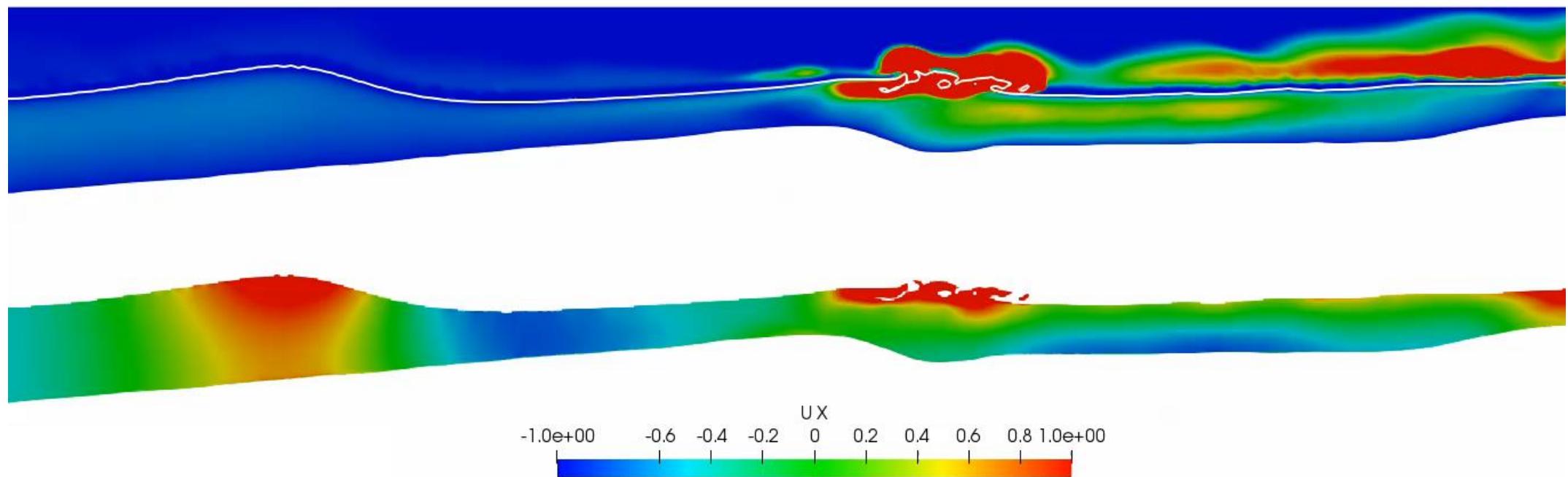
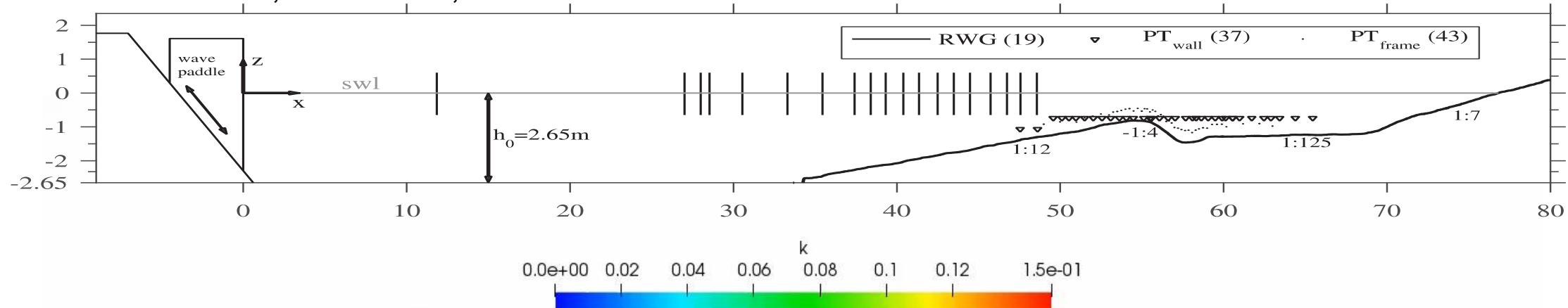


<https://github.com/BrechtDevolder-UGent-KULeuven/buoyancyModifiedTurbulenceModels>

Breaking waves over a fixed bar (plunging)

Experiments: van der A et al. (2017): Large-scale laboratory study of breaking wave hydrodynamics over a fixed bar, Journal of Geophysical Research: Oceans, vol. 122, pp. 3287–3310.

$$H = 0.85 \text{ m} ; T = 4.00 \text{ s} ; d = 2.65 \text{ m}$$

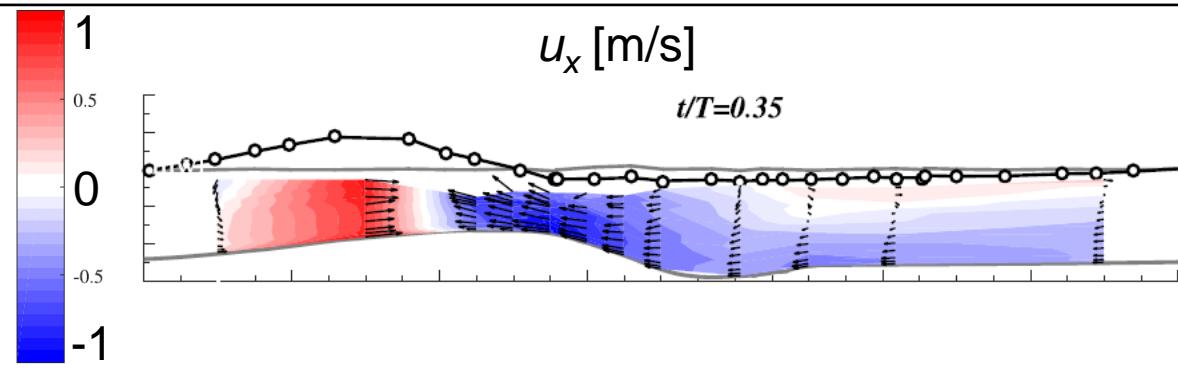


Breaking waves over a fixed bar (plunging)

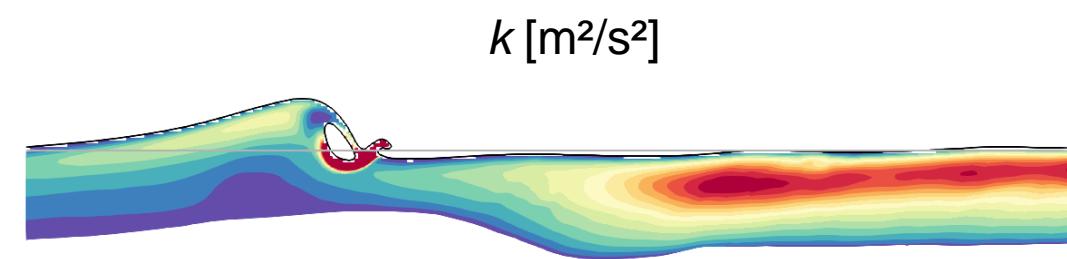
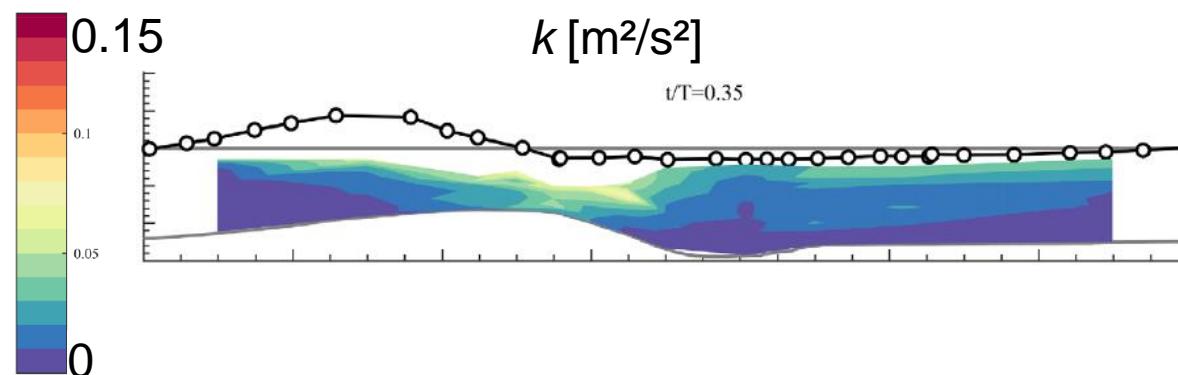
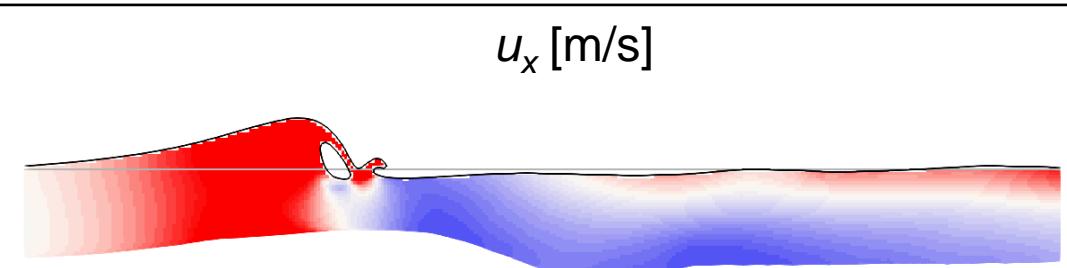
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Outlook: validation of surface elevations, velocity profiles and turbulent quantities

Experiments

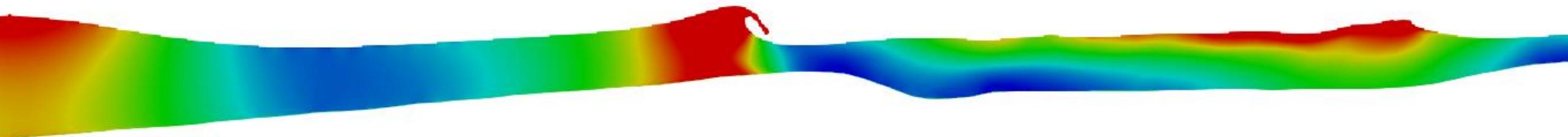


CFD simulation



Conclusions

- Enhanced wave modelling using buoyancy-modified RANS turbulence models
- No wave damping due to RANS turbulence modelling using a two-phase fluid solver
- More accurate predictions of the turbulent quantities in the flow field under breaking waves



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