

# A NEW HYBRID APPROACH IN THE CALIBRATION OF A BREAKING MODEL WITHIN A BOUSSINESQ-TYPE WAVE MODEL

Joaquín Moris<sup>1</sup>

Patricio Catalán<sup>2</sup>

Rodrigo Cienfuegos<sup>3</sup>

<sup>1</sup>PhD Student, University of Notre Dame, USA.

<sup>2</sup>Associate Professor, Universidad Técnica Federico Santa María, Chile.

<sup>3</sup>Associate Professor, Pontificia Universidad Católica de Chile, Chile.

# Motivation

- Can we assure that wave breaking models accurately predict the breaking location and its extension?
    - Usually wave breaking models are calibrated using free surface elevation measurements ( $\eta$ ):
      - Schäffer et al. (1993)
      - Kennedy et al. (2000)
      - Tonelli and Petti (2009)
      - Tissier et al. (2012)
      - Cienfuegos et al. (2010)
- Breaking models  
calibrated/validated  
using measurements of  $\eta$

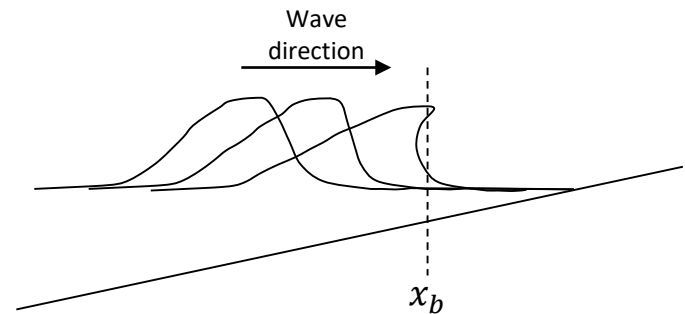
# Motivation

- Can we assure that wave breaking models accurately predict the breaking location and its extension?

– Some researchers have included the breaking location ( $x_b$ ) as a calibration element:

- Okamoto & Basco (2006)
- D'Alessandro & Tomasicchio (2008)

} Breaking models calibrated/validated using measurements of  $x_b$



# Motivation

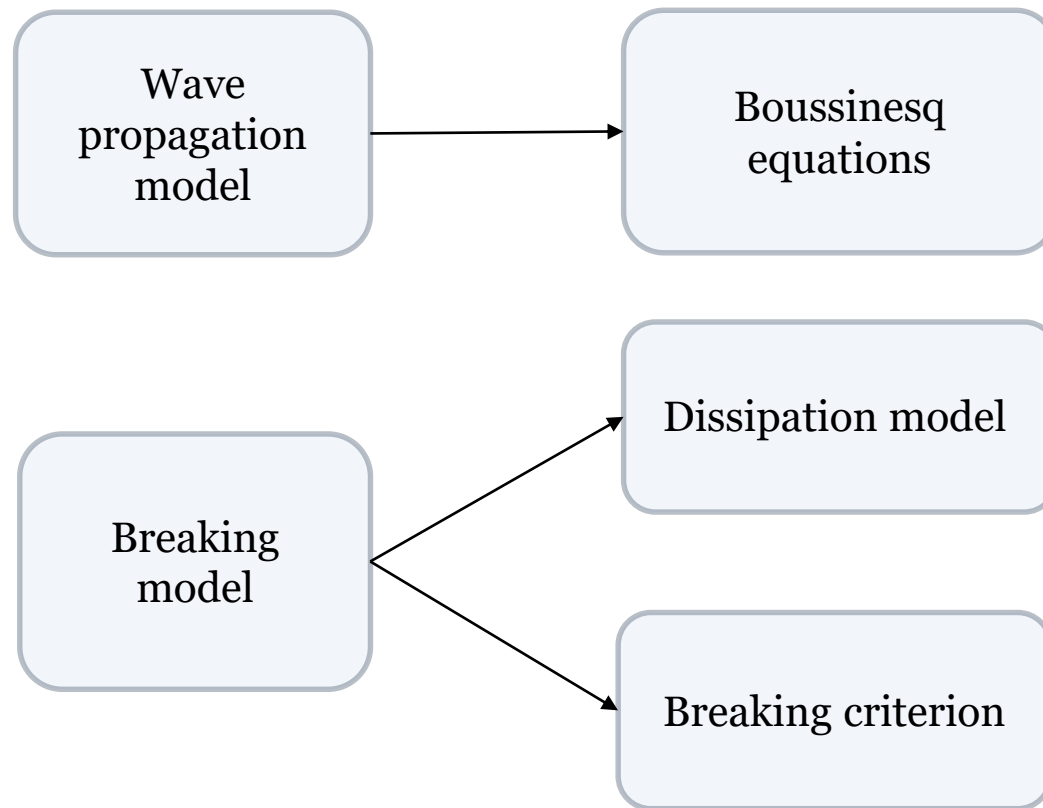
- What about the ending point of the breaking process?
- What about the length of the breaking process?

## Objective

Propose a calibration methodology that includes both measurements of  $\eta$  and the breaking process (initial and ending points), and therefore, its length.

# Numerical Model

- A 1D wave breaking model for Boussinesq-type equations was used (Cienfuegos et al. 2010)



# Wave propagation and dissipation model

$$\frac{\partial h}{\partial t} + \frac{\partial(hu)}{\partial x} - D_h = 0$$
$$\frac{\partial u}{\partial t} + \frac{1}{2} \frac{\partial(u^2)}{\partial x} + g \frac{\partial h}{\partial x} + \Gamma_d - \frac{1}{h} D_{hu} = 0$$

Terms associated with wave breaking

$h$ : local depth  
 $u$ : depth averaged horizontal velocity  
 $g$ : gravitational acceleration  
 $\Gamma_d$ : Boussinesq dispersive terms  
 $D_h, D_{hu}$ : breaking-induced contributions

- Dissipation model is represented with a parametric eddy viscosity model that acts in  $D_h$  and  $D_{hu}$ .

Details of the propagation and dissipation model?  
See Cienfuegos et al. (2010) or ask me at the end of the session.

# Wave Breaking Criterion

A simple breaking slope threshold angle was used as a breaking criterion (Cienfuegos et al., 2010).

- Breaking starts if the frontal angle of the wave exceeds  $\Phi_b$ :

$$\left| \frac{\partial \eta}{\partial x} \right| > \tan \Phi_b$$

$\Phi_b$ : parameter of the calibration

- Breaking stops if the frontal angle of the wave is less than  $\Phi_f$ :

$$\left| \frac{\partial \eta}{\partial x} \right| < \tan \Phi_f$$

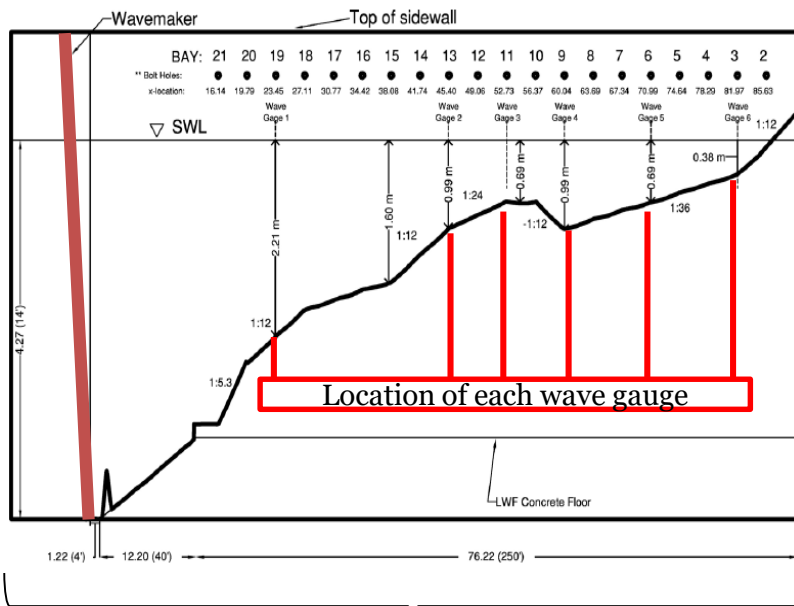
$\Phi_f$ : parameter of the calibration

# Experimental data

Free surface elevation ( $\eta$ ) and the wave breaking location were simultaneously recorded in a barred profile (scale 1:3) at the Large Wave Flume Lab at Oregon State University (Catalán & Haller, 2008).

Bathymetry data was recorded from a field experiment in Duck, NC.

$\eta$  -> Wave gauges



6 gauges recorded the free Surface elevation ( $\eta$ )

Breaking location -> Video cameras



Visual field of each camera



Top view (corrected) of the cameras

3 video cameras recorded the wave breaking location



# Experimental data

- Both a regular and an irregular wave cases were considered.

Wave run case	$T_p$ (s)	$H_0$ (m)	Breaker
Regular	4.0	0.64	<i>Spilling</i>
Irregular	2.7	0.37	<i>Spilling</i>

# Experimental data

How do we quantify the breaking location and its extension?

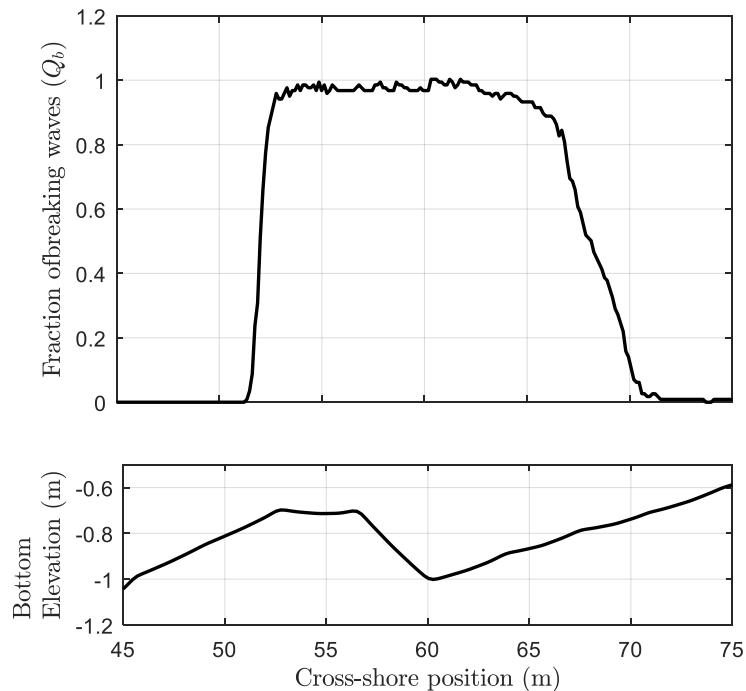
- Fraction of breaking waves  $Q_b(x)$ , defined as:

$$Q_b(x) = \frac{\# \text{ breaking waves}}{\# \text{ total waves}}$$

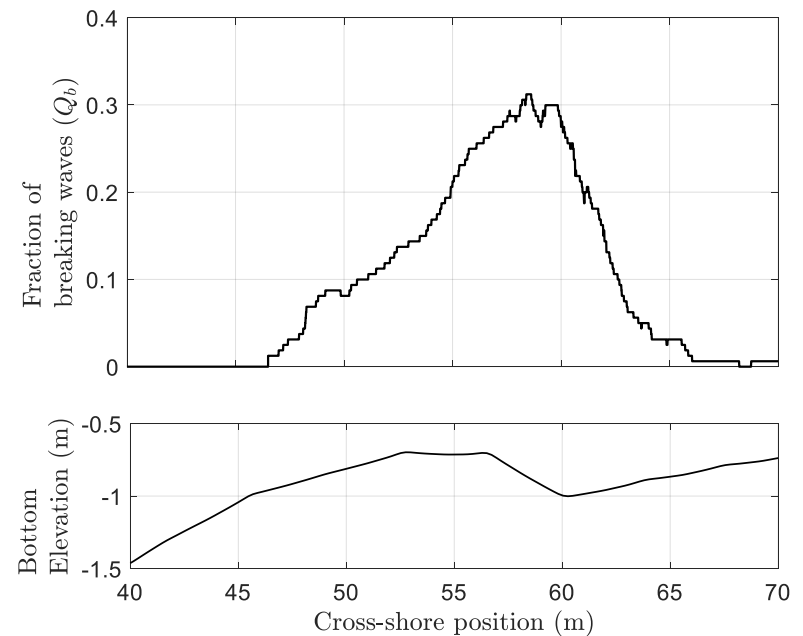
# Experimental data

$$Q_b(x) = \frac{\# \text{ breaking waves}}{\# \text{ total waves}}$$

## Regular run



## Irregular run



# Model calibration methodology

## Traditional calibration

Fit:

a) The root mean square of the wave height ( $H_{rms}$ )

$$H_{rms}(x) = \sqrt{\frac{1}{N_{waves}} \sum_{i=1}^{N_{waves}} (H_i(x))^2}$$

## Hybrid calibration

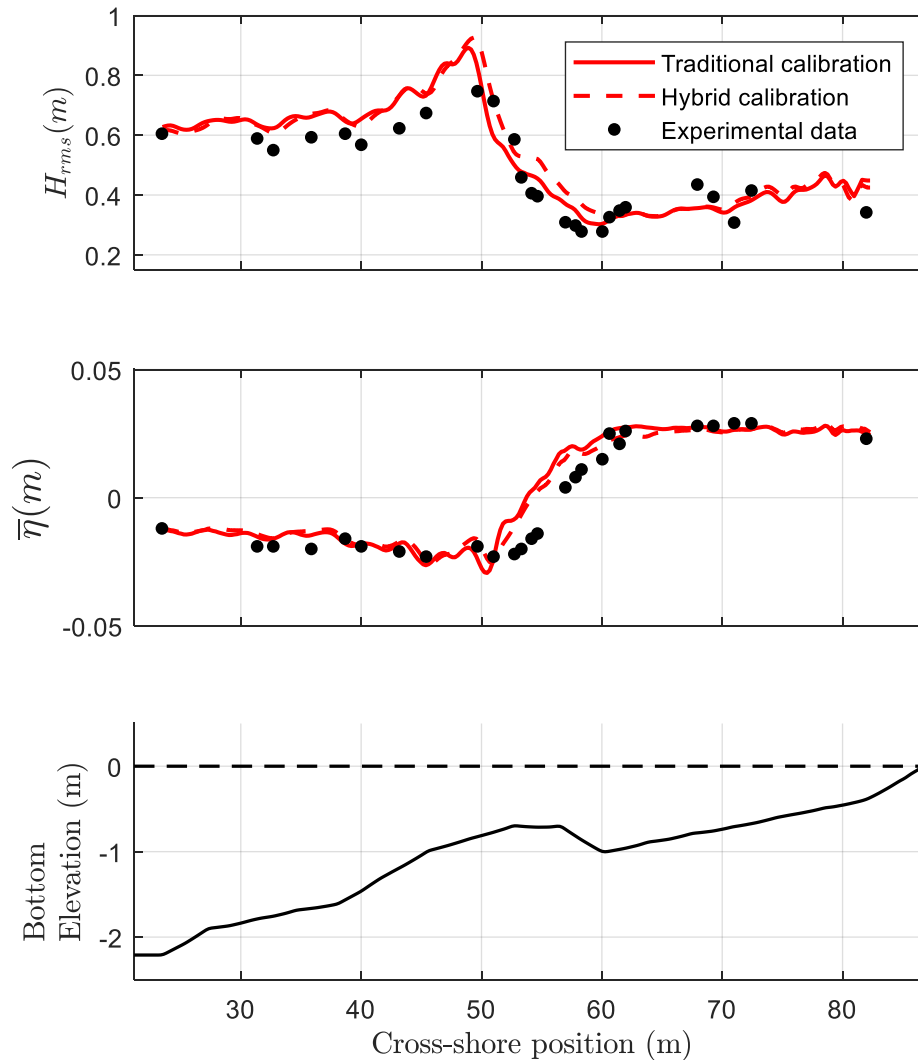
Fit both:

a) The root mean square of the wave height ( $H_{rms}$ )

b) The fraction of breaking waves ( $Q_b$ )

# Results and discussion

## Regular Waves

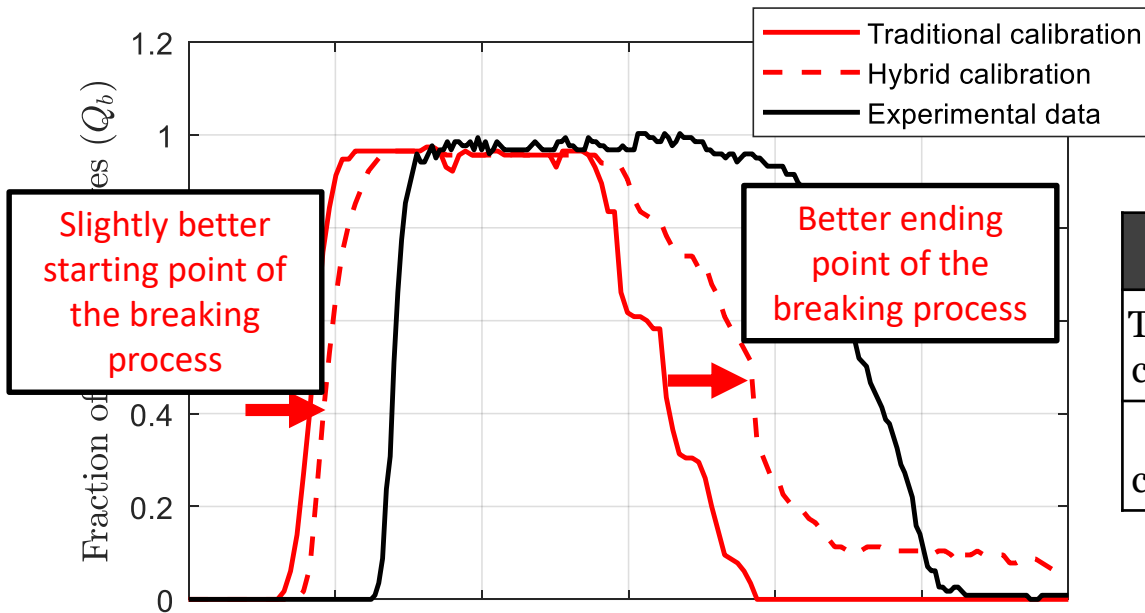


	$\Phi_b$	$\Phi_f$
Traditional calibration	42°	9°
Hybrid calibration	44°	8°

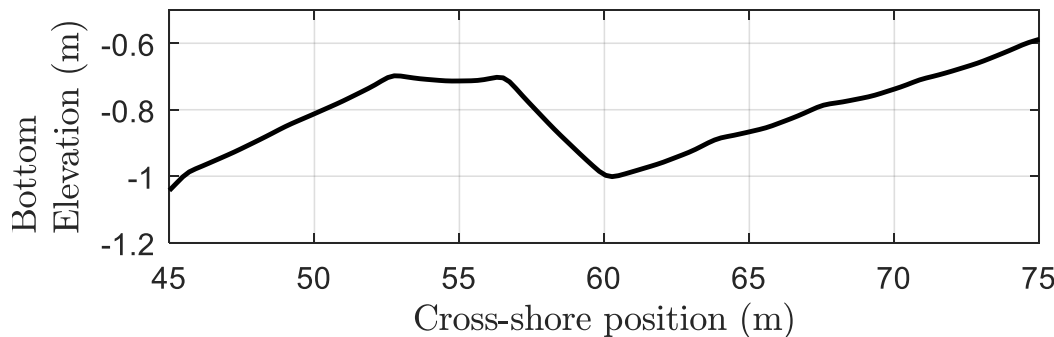
Both calibrations seem reasonable

# Results and discussion

## Regular Waves



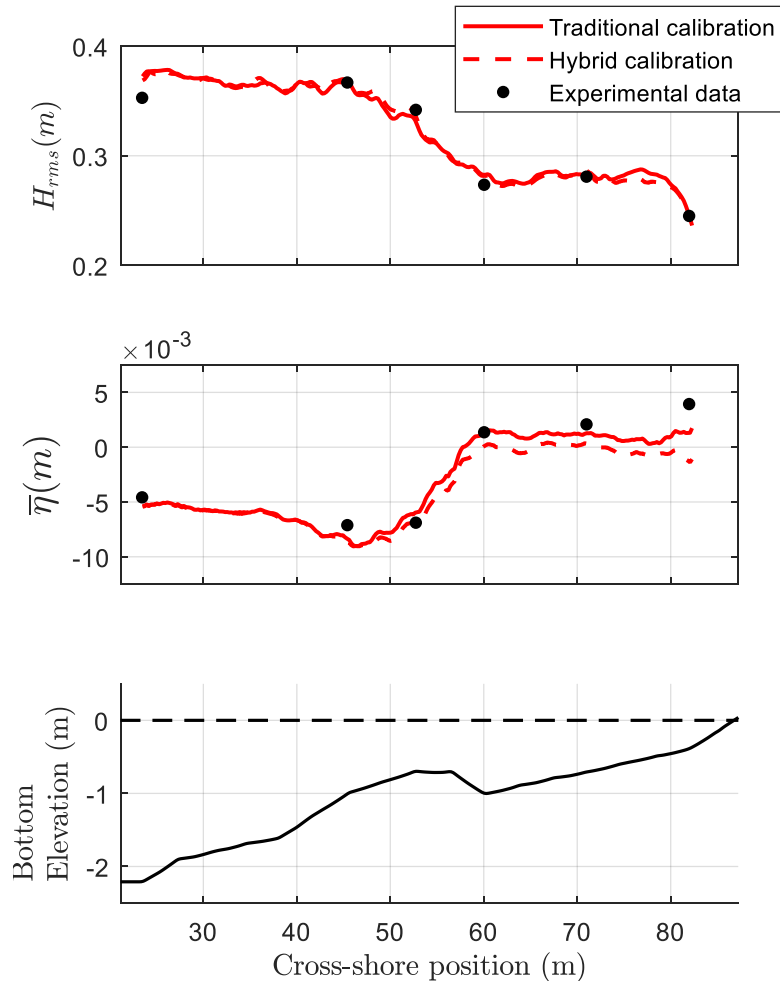
	$\Phi_b$	$\Phi_f$
Traditional calibration	42°	9°
Hybrid calibration	44°	8°



Both calibrations do not show the expected agreement

# Results and discussion

## Irregular Waves

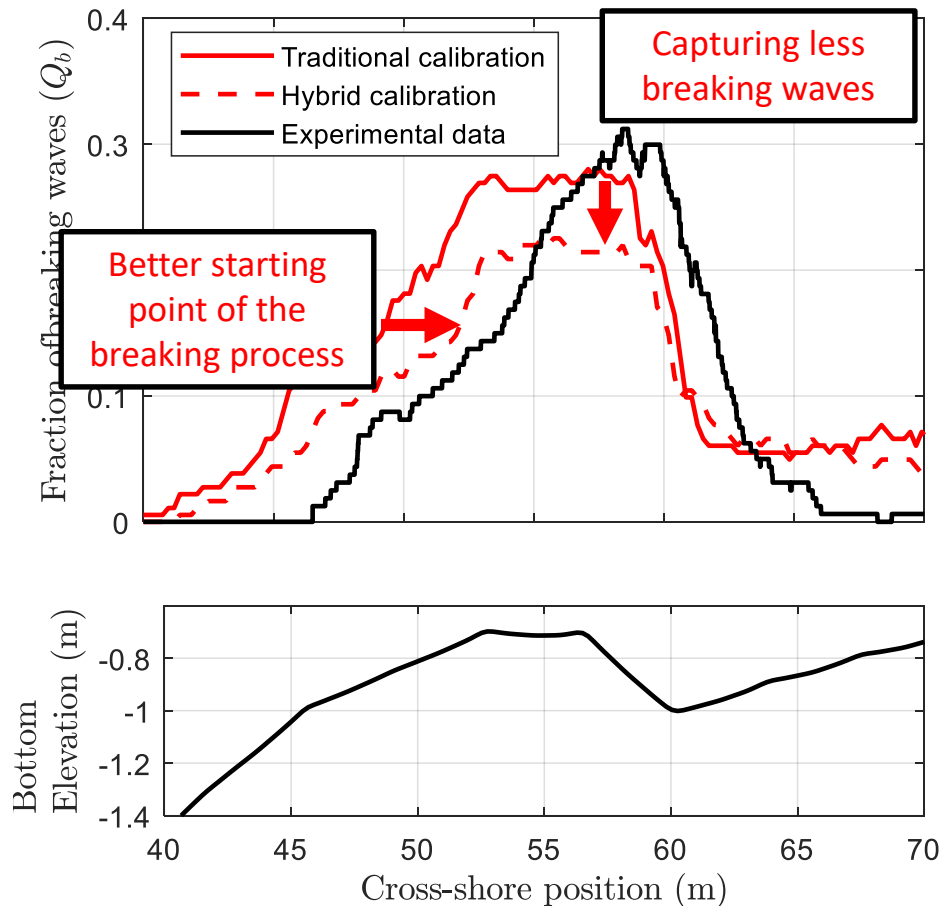


	$\Phi_b$	$\Phi_f$
Traditional calibration	$24.5^\circ$	$8.0^\circ$
Hybrid calibration	$28^\circ$	$6.5^\circ$

Again, both calibrations seem reasonable

# Results and discussion

## Irregular Waves



	$\Phi_b$	$\Phi_f$
Traditional calibration	24.5°	8.0°
Hybrid calibration	28°	6.5°

Both calibrations do not show the expected agreement



# A different wave breaking criterion: Breaking Celerity Index (BCI) (D'Alessandro & Tomasicchio, 2008)

Undular hydraulic jump

Non-breaking wave



Fully developed hydraulic jump

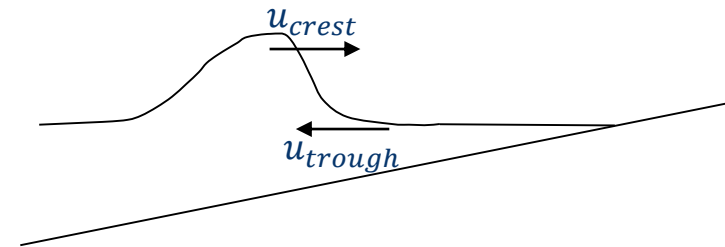
Breaking wave



- Breaking starts if:

$$\frac{\partial \eta}{\partial t} \geq BCI \quad BCI = \frac{u_{crest} - u_{trough}}{CTFN}$$

*CTFN*: Critical Trough Froude Number



*CTFN*: parameter  
of the calibration

# A different wave breaking criterion: Breaking Celerity Index (BCI) (D'Alessandro & Tomasicchio, 2008)

- Two different breaking ending criteria were implemented.

1) From Kennedy et al. (2000):

Breaking ends if  $\frac{\partial \eta}{\partial t} < \eta_t^*$

$$\eta_t^* = \begin{cases} b_2 \sqrt{gh} & t - t_b \geq T^* \\ b_1 \sqrt{gh} + \frac{t - t_b}{T^*} (b_2 - b_1) \sqrt{gh} & 0 \leq t - t_b < T^* \end{cases}$$

$T^*$ : Transition time.  $T^* = 5\sqrt{h/g}$

$t_b$ : time when breaking was initiated

Calibrate: CTFN,  $b_1$ ,  $b_2$

2) Breaking slope threshold angle (Cienfuegos et al., 2010)

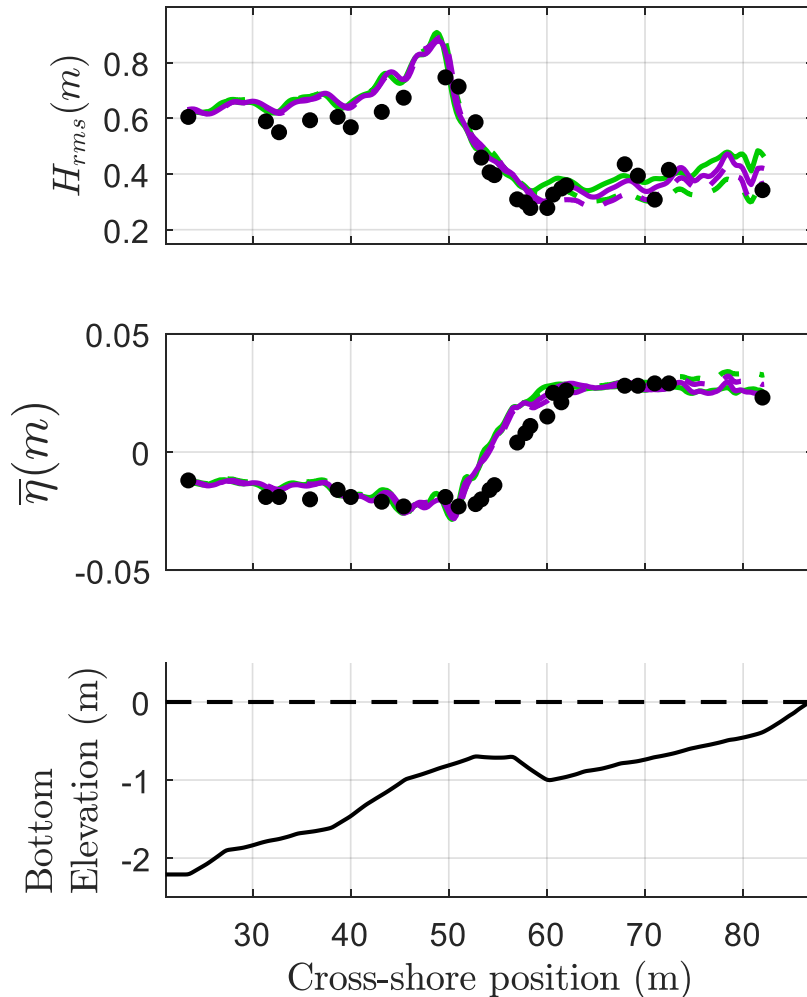
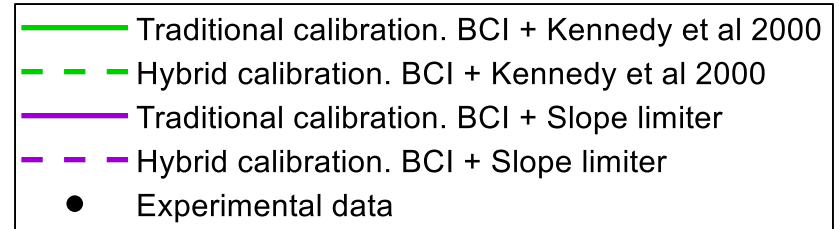
Breaking ends if

$$\left| \frac{\partial \eta}{\partial x} \right| < \tan \Phi_f$$

Calibrate: CTFN,  $\Phi_f$

# Results and discussion

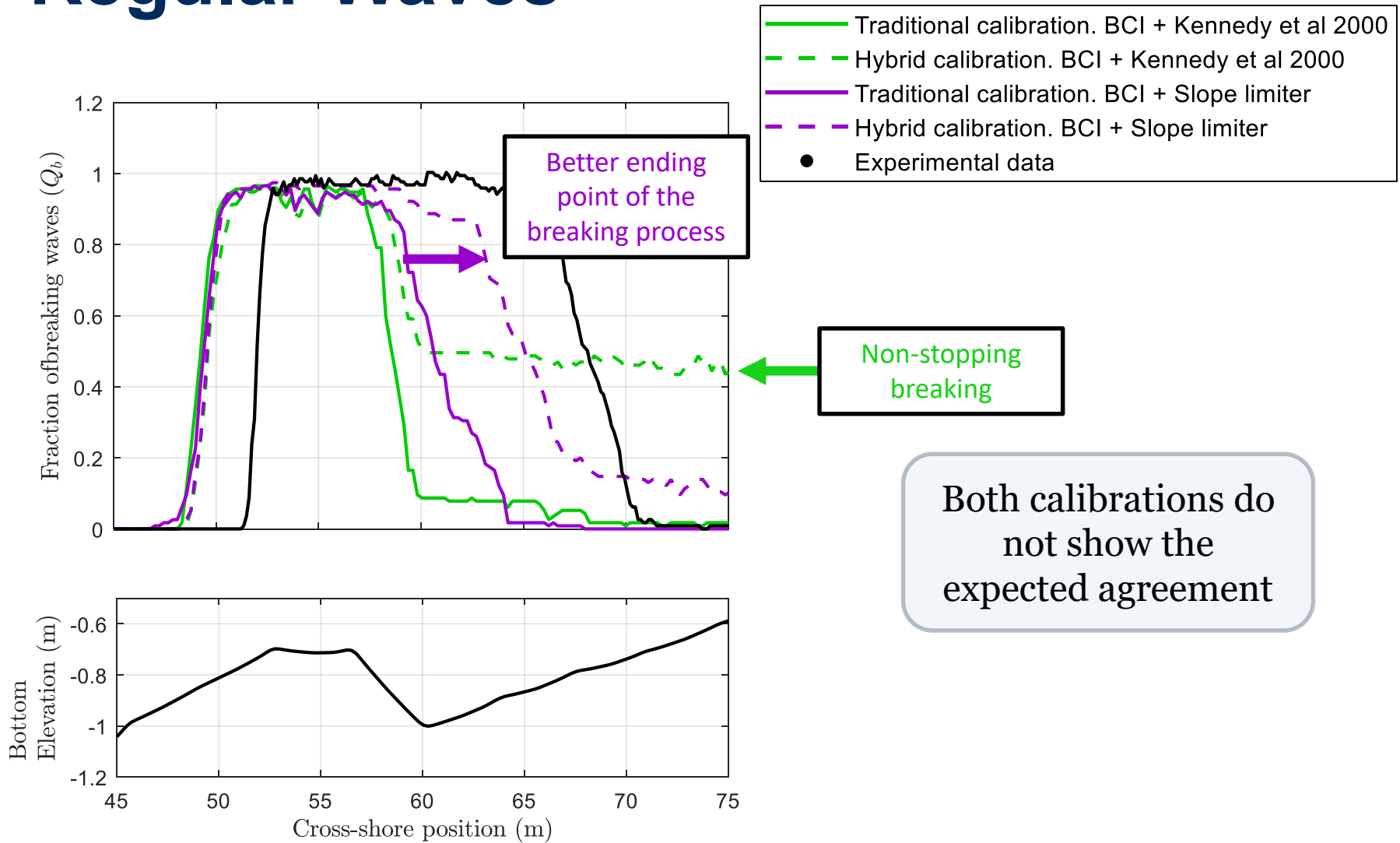
## Regular Waves



All the calibrations  
seem reasonable

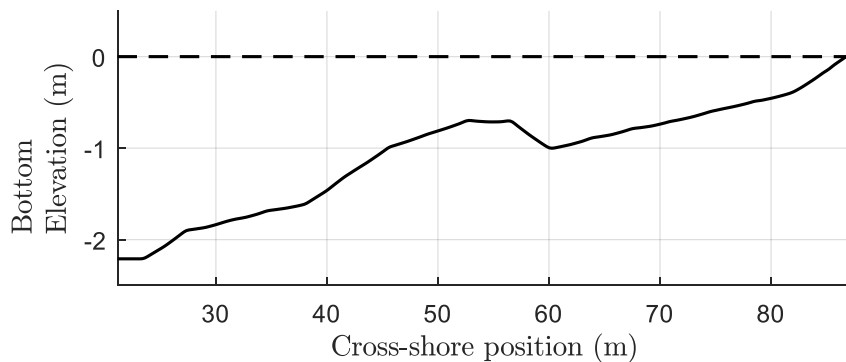
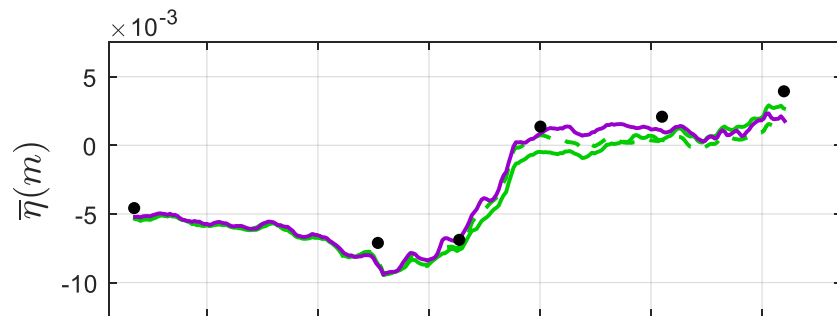
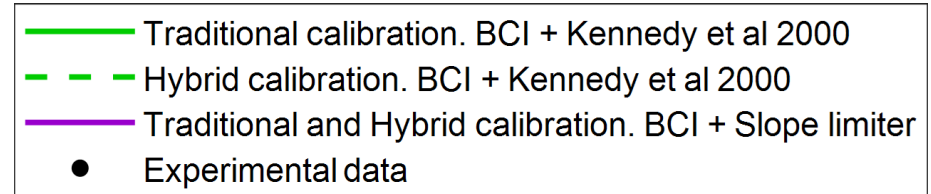
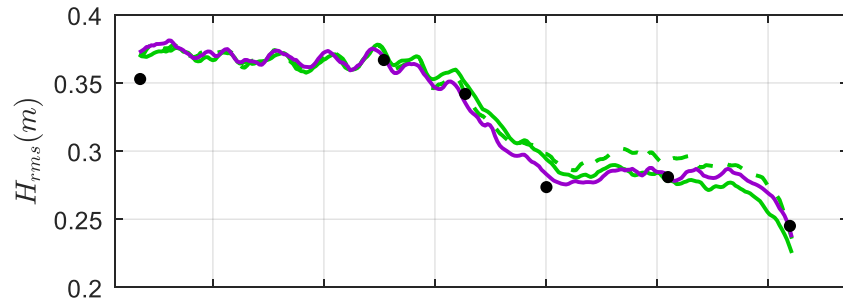
# Results and discussion

## Regular Waves



# Results and discussion

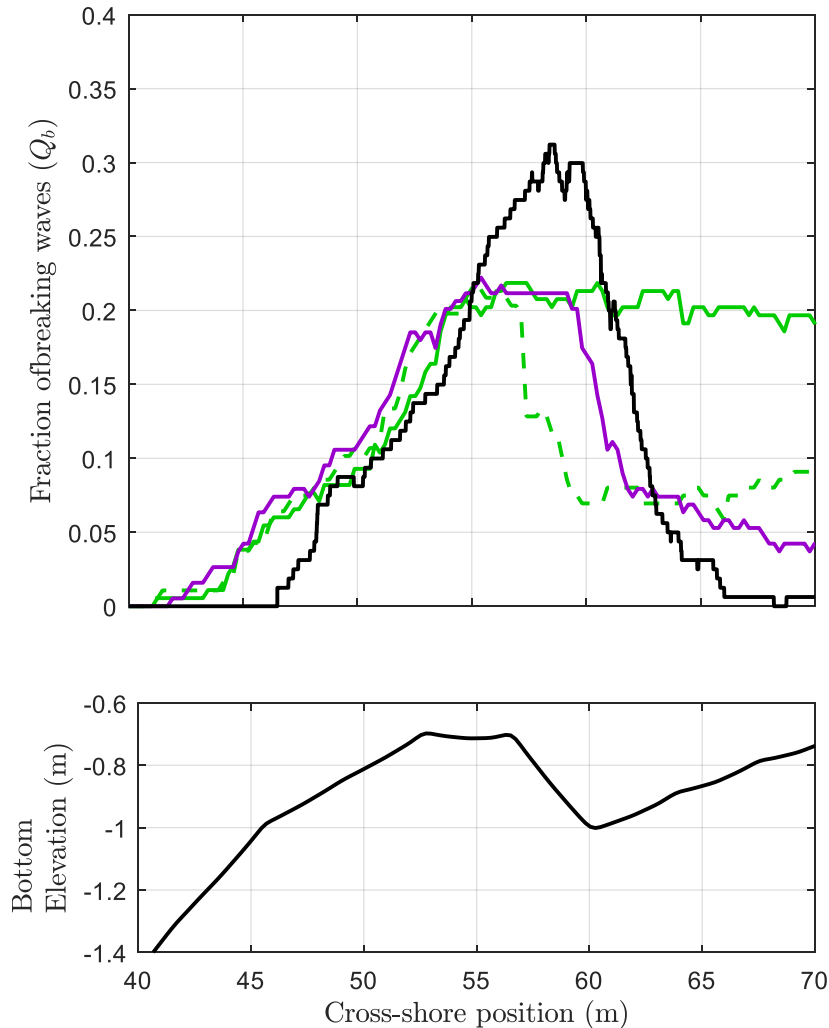
## Irregular Waves



All the calibrations  
seem reasonable

# Results and discussion

## Irregular Waves



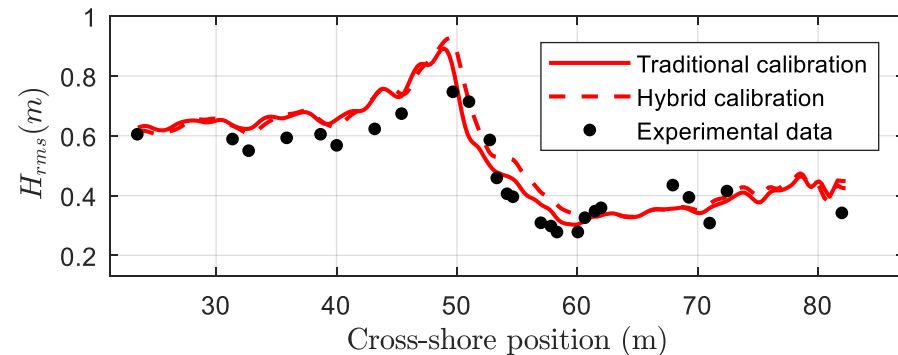
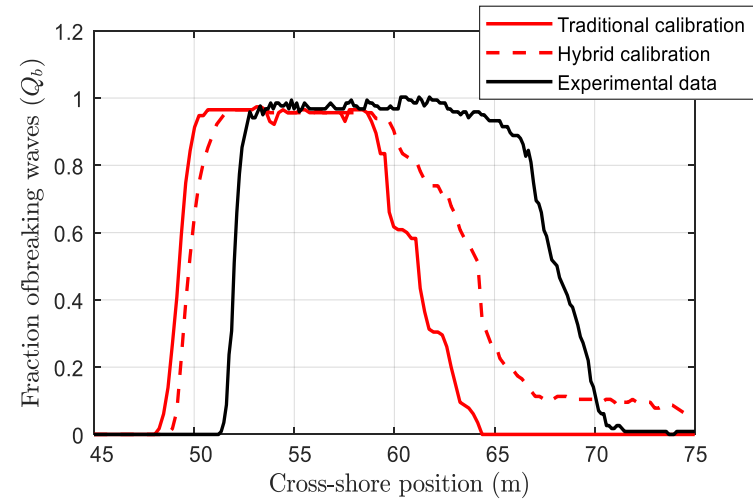
- Traditional calibration. BCI + Kennedy et al 2000
- - - Hybrid calibration. BCI + Kennedy et al 2000
- Traditional and Hybrid calibration. BCI + Slope limiter
- Experimental data

Non-stopping  
breaking

Both calibrations do  
not show the  
expected agreement

# Conclusions

- The hybrid calibration can improve the parameter selection of a breaking model.
- Without the use of the video cameras, irregularities in the location of the breaking process go unnoticed.
- Achieving a good fit of both the water levels and the breaking process is a challenge for the presented breaking models, which might require adjustments on their original formulation.



**THANK YOU FOR YOUR ATTENTION**