LABORATORY STUDY OF RUBBLE FOUNDATIONS FOR VERTICAL BREAKWATERS

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ABSTRACT

Laboratory tests have been conducted to determine the stability characteristics of pell-mell placed rubble of sensibly uniform shape and size used as a foundation or as toe protection for the vertical superstructure of a composite breakwater. Data are presented for the design of such breakwater foundations.

INTRODUCTION

An investigation is being conducted in the Hydraulic Laboratories at Queen's University at Kingston, on the behaviour under wave attack of the rubble portion of a composite breakwater consisting of a vertical breakwater atop a rubble-mound.

This study is part of a general program on harbour problems on the Great Lakes of Canada and is a preliminary effort to provide a rational basis for the design of such rubble sections to withstand the erosive action of waves.

The forces exerted by wind-generated waves on breakwaters and allied structures have, for many years, been the subject of theoretical, laboratory and field study. Most of this effort has been directed towards evaluating the effects of waves on rubble-mound breakwaters, Iribarren (1951), Beaudevin (1955) and Hudson (1959), and the forces exerted on the face-walls of vertical breakwaters, Minikin (1950) and Nagai (1960).

Apparently no systematic study of the well recognized problem of erosion of the foundations (usually rubble-mound) of composite breakwaters has been made.

Figure 1 illustrates the three main types of breakwater, 1(c) being the type under investigation. This latter type might well be selected instead of the purely vertical structure for the following cases:

a) where the seabed has insufficient strength to bear the concentrated loads associated with vertical gravity walls;
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(a) TYPICAL RUBBLE MOUND BREAKWATER

(b) TYPICAL VERTICAL WALL BREAKWATER

(c) TYPICAL COMPOSITE BREAKWATER

Fig. 1. Breakwater cross-sections.

Fig. 2. Composite breakwater under wave attack (Definitions of nomenclature).
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b) where scour of the bed material is a problem;

c) where great depths make it uneconomical to build a rubble-mound breakwater - a 33% increase in height requires a 50% increase in volume of stone for the same side-slopes and top width of rubble-mound.

From a practical viewpoint the design of the superstructure of the composite breakwater may follow established procedures, B.E.B. (1961), whereas the necessary size and weight of stone for the foundation portion is, at present, a matter of engineering judgement.

In what follows an attempt is made to make the selection of stone size a rational one based on extrapolated laboratory tests.

STABILITY ANALYSIS

The forces on an individual unit of a rubble mound foundation of a vertical wall situated at a depth $d_1$ below the S.W.L. will be considered. The conditions are illustrated in Figure 2. The disturbing force is taken to consist of inertia and drag components. The inertia force on a body submerged in an oscillating fluid is proportional to the product of the volume of the body, the mass of the fluid and the local acceleration of the fluid; thus

$$F_I = C_I \rho \frac{d}{g} \frac{\partial v}{\partial t}$$

where $C_I$ is an inertia coefficient. (Notation is defined in the appendix.)

The drag force on a body in an oscillating fluid is proportional to the product of the cross-sectional area of the body, the mass of the fluid, and the square of the velocity of the oscillating fluid; thus

$$F_D = \frac{1}{2} C_D \rho \frac{d}{g} v \|v\|$$

where $C_D$ is a drag coefficient.

In the case of the rubble unit of the foundation under study, the velocities and accelerations in the vicinity of the rubble unit are not known since the presence of the mound modified the orbital velocities and accelerations which would exist in the clapotis arising from a vertical wall with no mound in front of it. However, it will be assumed that the velocities and accelerations actually existing around the rubble units are directly proportional to those which would exist at the corresponding depth in a total clapotis. A rubble unit will be subjected to disturbing forces with horizontal and vertical components. The restoring force will be the buoyant weight. Considering incipient horizontal displacement of the unit, the condition of limiting equilibrium is:

$$\sum F_H = \mu \sum F_V$$

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where $\Sigma F_H = \text{sum of horizontal forces}$

$\Sigma F_V = \text{sum of vertical forces}$

$\mu = \text{friction coefficient}$

$\Sigma F_H = \text{Horizontal Inertia Force + Horizontal Drag Force}$

$$= F_{HI} + F_{HD} \quad (4a)$$

$\Sigma F_V = \text{Buoyant Weight + }|\text{Vertical Inertia Force}| + |\text{Vertical Drag Force}|$

$$= \text{Buoyant Weight + } F_{VI} + F_{VD} \quad (4b)$$

According to first order gravity wave theory, the horizontal and vertical components of orbital velocity and acceleration, in a total clapotis at a depth $d_t$ below the S.W.L. where the water depth is $d$, are:

$$U = Hk \frac{\cosh md (1 - d/d)}{\sinh md} \sin mx \sin kt$$

$$= U_{max} \sin kt \quad (5a)$$

where $U_{max}$ denotes the maximum horizontal component of orbital velocity at a point. Similarly,

$$v = -Hk \frac{\sinh md (1 - d/d)}{\sinh md} \cos mx \sin kt$$

$$= -v_{max} \sin kt \quad (5b)$$

$$\frac{\partial u}{\partial t} = Hk^2 \frac{\cosh md (1 - d/d)}{\sinh md} \sin mx \cos kt$$

$$= \left[ \frac{\partial u}{\partial t} \right]_{max} \cos kt \quad (5c)$$

$$\frac{\partial v}{\partial t} = -Hk^2 \frac{\sinh md (1 - d/d)}{\sinh md} \sin mx \cos kt$$

$$= -\left[ \frac{\partial v}{\partial t} \right]_{max} \cos kt \quad (5d)$$
Recalling equations (1) and (2), the horizontal and vertical force components are written:

**Horizontal Inertia Force** \( (F_{HI}) \)

\[
F_{HI} = C_{MH} D^3 \left( \frac{\dot{y}}{g} \right) \left[ \frac{\partial u}{\partial t} \right]_{\text{max}} \cos kt \quad (6a)
\]

**Horizontal Drag Force** \( (F_{HD}) \)

\[
F_{HD} = \frac{1}{2} C_{DH} D^2 \left( \frac{\dot{y}}{g} \right) u_{\text{max}}^2 \sin kt \sin kt \quad (6b)
\]

**Vertical Inertia Force** \( (F_{VI}) \)

\[
F_{VI} = -C_{MV} D^3 \left( \frac{\dot{y}}{g} \right) \left[ \frac{\partial v}{\partial t} \right]_{\text{max}} \cos kt \quad (6c)
\]

**Vertical Drag Force** \( (F_{VD}) \)

\[
F_{VD} = \frac{1}{2} C_{DV} D^2 \left( \frac{\dot{y}}{g} \right) u_{\text{max}}^2 \sin kt \sin kt \quad (6d)
\]

The coefficients \( C_{MH}, C_{DH}, C_{MV}, \) and \( C_{DV} \) are the appropriate horizontal and vertical inertia and drag coefficients whose values take care of the discrepancy between actual and assumed velocities and accelerations.

**Buoyant Weight**

\[
\beta D^3 (\gamma_f - \gamma) \quad (6e)
\]

where the coefficient \( \beta \) depends on the shape of the unit.

It is evident that the maximum values of the above periodic forces do not occur at the same time. However, movement of the stone in question is initiated by action of vertical wave forces, which reduce the effective buoyant weight of the stone, simultaneous with, or closely followed by, a horizontal wave force which tends to displace the "lightened" stone. It will further be assumed that the "lightening" action is effected by the combined efforts of the maximum vertical inertia and drag forces, and that the disturbing force is given by the combined efforts of the maximum horizontal inertia and drag forces. Since here we are dealing with proportionalities rather than real, actual forces, this simplification is justified. Therefore, dropping the periodic terms of equation (6) which define the magnitude and direction of each component force at the particular point, the equation of limiting equilibrium is written:
\[ C_{\text{MH}} D^3 (\phi_f / g) \left[ \frac{\partial u}{\partial t} \right]_{\text{max}} + \frac{1}{2} C_{\text{DH}} D^2 (\phi_f / g) \cdot u_{\text{max}}^2 \]

\[ = \mu \left\{ \beta D^3 (\phi_f - \phi_f) - C_{\text{MV}} D^3 (\phi_f / g) \left[ \frac{\partial v}{\partial t} \right]_{\text{max}} - \frac{1}{2} C_{\text{DV}} D^2 (\phi_f / g) \cdot v_{\text{max}}^2 \right\} \]

Since the weight of the rubble unit = \( W_r = \beta D^3 \phi_f \), we have

\[ \frac{W_r}{\phi_f} = \frac{\beta}{8} \left[ C_{\text{DH}} u_{\text{max}}^2 + C_{\text{DV}} v_{\text{max}}^2 \right] \left( \mu g (S_r - 1) - \left\{ C_{\text{MH}} \left[ \frac{\partial u}{\partial t} \right]_{\text{max}} + \mu C_{\text{MV}} \left[ \frac{\partial v}{\partial t} \right]_{\text{max}} \right\} \right)^3 \]

where \( S_r = \frac{\phi_f}{\phi_f} \)

Now recalling from equation (5) the values of \( u_{\text{max}}, v_{\text{max}}, \left[ \frac{\partial u}{\partial t} \right]_{\text{max}} \) and \( \left[ \frac{\partial v}{\partial t} \right]_{\text{max}} \), substituting these values in the above equation, and then multiplying both sides of the resulting equation by \( \left[ \frac{S_r - 1}{H} \right]^3 \) gives:

\[ \frac{W_r (S_r - 1)}{H^3 \phi_f} \left( \frac{\beta}{8} \right)^3 = \frac{\beta}{8} \left[ C_{\text{DH}} \frac{\cosh^2 m d (1 - d_i / d)}{\sinh^2 m d} + C_{\text{DV}} \frac{\sinh^2 m d (1 - d_i / d)}{\sinh^2 m d} \right] \]

\[ \left( \frac{\mu g}{H^2} - \frac{1}{S_r - 1} \right) \left\{ C_{\text{MH}} \frac{\cosh m d (1 - d_i / d)}{\sinh m d} + \mu C_{\text{MV}} \frac{\sinh m d (1 - d_i / d)}{\sinh m d} \right\} \]

Now, if we put \( C_{\text{DV}} = \sigma_1 C_{\text{DH}}, C_{\text{MV}} = \sigma_2 C_{\text{MH}} \) and \( \mu = 1 \), recall that:

\[ k = 2\pi / T \]

\[ L = (g T^2 / 2\pi) \tanh m d \]

and adopt the notation of Hudson (1959) by writing the above equation in terms of the Stability Number, \( N_S \), such that

\[ N_S = \frac{\gamma_{\phi_f} H}{W_r (S_r - 1)} \]

the result is:

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Fig. 3. Model test conditions.

(b) RUBBLE MOUND USED AS TOE PROTECTION

Notes: (1) Width of test channel was 20 inches
(2) Average distance of model from wave generator was 40 ft.

Fig. 4a

Fig. 4b

Fig. 4. Model test conditions for rubble mound as a foundation.
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Although equation 7(a) is based on very simplified assumptions and contains a number of unknown coefficients, it does serve the useful purpose of identifying the principal parameters involved in the problem. These may be listed as follows:

1) the term \( \beta \), i.e. related to the shape of the rubble units, \( \Delta \).
2) the term \( \frac{C_{DH}}{C_{MH}} \), i.e. related to the ratio of inertia and drag coefficients, \( \frac{C_D}{C_M} \).
3) the term \( \frac{1}{C_{MH}} \), i.e. related to the product of wave steepness and inertia coefficient, \( C_M H / L \).
4) the specific gravity of the rubble units, \( S_r \).
5) the term \( m d \), i.e. related to the relative depth, \( d / L \).
6) the relative depth of the foundation with reference to the S.W.L., \( d_1 / d \).

Therefore the Stability Number may be written:

\[
N_s = f(\Delta, \frac{C_D}{C_M}, \frac{C_M H}{L}, S_r, d / L, \text{and } d_1 / d) \tag{7(b)}
\]

where \( f \) reads "a function of".

EXPERIMENTAL WORK

A series of experiments was carried out to investigate the influence of the various parameters as noted in equation (7) on the Stability Number.

Figure 3 illustrates the experimental conditions and Figure 4 shows photographs of the installation under test.

Range of Test Conditions: The following tabulation gives the ranges of wave characteristics and breakwater dimensions used in the tests:

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Characteristics and Dimensions

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Range of Test Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Water depth (d)</td>
<td>1.00 ft.</td>
</tr>
<tr>
<td>Wave height (H)</td>
<td>0.04 to 0.445 ft.</td>
</tr>
<tr>
<td>Wave period (T)</td>
<td>1.00 to 2.00 secs.</td>
</tr>
<tr>
<td>Wave length (L)</td>
<td>4.51 to 10.76 ft.</td>
</tr>
<tr>
<td>Relative depth (d/L)</td>
<td>0.0930 to 0.2215</td>
</tr>
<tr>
<td>Wave steepness (H_{\text{crit}}/L)</td>
<td>at limiting equilibrium</td>
</tr>
<tr>
<td>Specific weight of stone (\rho_s)</td>
<td>165.4 lbs./cu.ft.</td>
</tr>
<tr>
<td>Average weight of individual rubble units (W_r)</td>
<td>0.00183 to 0.0190 lbs.</td>
</tr>
<tr>
<td>Specific weight of water (\rho_f)</td>
<td>62.4 lbs./cu.ft.</td>
</tr>
<tr>
<td>Relative depth of top surface of foundation mound below S.W.L. (d_1/d)</td>
<td>0.00 to 0.75</td>
</tr>
<tr>
<td>Top width of foundation mound on seaward side (B)</td>
<td>0.15 d to 0.75 d</td>
</tr>
</tbody>
</table>

(Note: Main body of tests conducted at B = 0.4d)

Slope of foundation mound on seaward side | 1 on 2
Crown elevation of vertical superstructure | No overtopping
Test sections | See Figure 3

Most of the tests were conducted with a top width of the foundation mound on the seaward side, B, of four-tenths the water depth (i.e. B = 0.4d), and zero penetration of the vertical superstructure into the rubble mound foundation. Additional tests, in which the top width, B, and the penetration of the superstructure into the foundation mound were varied, are discussed in the section headed SUPPLEMENTARY TESTS.

In the experiments, the shape, A, of the rubble units was kept sensibly constant, sub-rounded to sub-angular beach gravel of specific gravity 2.65 being used throughout. Four different stone sizes were used to correlate the parameters, 3/4"-5/8", 5/8"-1/2", 1/2"-3/8", 3/8"-1/4". The grading curves within each size range showed that the distribution of sizes was very similar in all cases; that is, similitude of size variation was being closely followed.

Since neither the drag nor the inertia coefficient of the stone was determined experimentally the data of Keulegan and Carpenter (1958) was used to provide an indication of the likely variations in the magnitude of these coefficients in the range of laboratory conditions encountered. These data indicated that the variation in numerical value was small over a wide range of wave steepnesses and stone sizes.

Thus the effective functional equation guiding the experimental work was reduced to the form
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\[ N_s = \frac{d_{1/3}}{H} = f\left(\frac{d}{L}, \frac{d}{d}, \text{and} \frac{H}{L}\right) \quad (8) \]

and each of these dimensionless terms was investigated as outlined in the following.

For given fixed values of \( \frac{d}{d} \) and \( T \), i.e. a fixed value of wavelength, a foundation of one size of stone was tested with increasing values of wave-height, \( H \). At small values of \( H \) no movement of the stone was discernable whereas at high values of \( H \) the rubble either rocked violently or was washed out from under the superstructure. It was consistently found that a relationship of the form shown in Figure 5 existed between \( H \) and the number of stones rocking at the base of the vertical superstructure. The point of critical stability normally occurred when about four pieces per lineal foot were rocking; but, as might be expected, this critical condition was not always exactly definable. However by plotting the test results as definitely stable (sensibly no movement) or unstable (wash out of at least two pieces) it was possible, as is seen in a typical test result, Figure 6, to arrive at a reasonably accurate relationship between stone size and wave height at the point of limiting equilibrium between stable and unstable conditions.

Using the curve defining the conditions of limiting equilibrium for a given stone weight (under the fixed values of \( \frac{d}{d} \) and \( L \)) the ratio \( \frac{d_{1/3}}{H_{\text{crit}}} \) was calculated and plotted against the wave steepness \( \frac{H_{\text{crit}}}{L} \). Such a plot is shown on Figure 7 and gives evidence of little effect of \( \frac{H_{\text{crit}}}{L} \) on \( N_s' \).

From the whole series of tests treated in this manner with varying values of \( \frac{d}{d} \) and \( T \) (and hence \( L \) and \( \frac{d}{L} \)) it was found that the critical stability number \( N_s' \) could, as a first approximation, be regarded as independent of the wave steepness \( H_{\text{crit}}/L \). In view of this, the mean value of \( N_s' \) as determined from the tests on the four sizes of stone was calculated and this mean value used to determine subsequent relationship between \( N_s' \) and \( \frac{d}{L} \) or \( \frac{d}{d} \).

Figure 8 shows the variation of the critical stability number with \( \frac{d}{L} \) using \( \frac{d}{d} \) as a parameter.

Again it appears from Figure 8 that relative depth \( \frac{d}{L} \) is of secondary importance except where the depth of the foundation below S.W.L. is great. However, since it is possible to achieve a range of values of \( \frac{d}{L} \) in a wave system in nature, the value of \( N_s' \) for the worst case of \( \frac{d}{L} \) (i.e. the lowest point on each \( N_s' \) versus \( \frac{d}{L} \) curve) is selected and plotted against \( \frac{d}{d} \).
Fig. 5

Fig. 6
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\[ N_s = \frac{f_{p}^{3/2} H_{\text{crit}}}{W_r (S_0 - 1)} \]

INCIDENT WAVE STEEPNESS, \( H_{\text{crit}} / L \)

\[ B/d = 0.40 \]
\[ T = 2.00 \text{sec.} \]
REFER TO FIG 6

\[ d_1/d = 0.75 \]

\[ d_1/d = 0.75, \ 0.50, \ 0.25, \ 0.00 \]

Fig. 7

Fig. 8. Rubble mound as a foundation. Critical stability number, \( N_s \), as a function of relative depth, \( d/L \).
Fig. 9. Comparison of test results for composite breakwaters with results of Hudson (1958) for rubble mound breakwaters.

Fig. 10. Rubble mound as toe protection; critical stability number, \( N'_s \), as a function of relative depth, \( d/L \).
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Such a plot derived from Figure 8 is shown in Figure 9 along with Hudson's test results. (The comparison with the latter's results is permissible since Hudson used somewhat the same criterion of damage/no damage or stable/unstable conditions.)

SUPPLEMENTARY TESTS

Top Width of Mound:

In this series of tests the top width of the foundation mound, \( B \), on the seaward side was varied. (Reference may be made to Figure 3.) The additional widths tested were \( B = 0.15d \) and \( B = 0.75d \). These tests were conducted only for the foundation depth \( d_1/d = 0.50 \) and \( d_1/d = 0.75 \).

It was found that variation in the top widths within the range stated above, did not result in significantly different Critical Stability Numbers from those already presented in Figure 8 for a foundation top width, \( B = 0.4d \).

Penetration of Superstructure in Mound:

To obtain an estimate of the effect of increasing the penetration of the superstructure into the mound foundation, the conditions illustrated in Figure 3(b) were tested. Here the superstructure extended to the floor of the wave tank and the rubble mound was piled in front to act as a toe protection. The results of these tests are depicted in Figure 10 where the variation of the Critical Stability Number, \( N_s \), with \( d/L \) and \( d_1/d \) is shown.

PRACTICAL APPLICATION OF RESULTS TO PROTOTYPE STRUCTURES

Test results have, so far, been presented in terms of a Critical Stability Number, \( N_s \), on the assumption that the structure was at the point of limiting equilibrium and that its ultimate safety was in some doubt. In the design of a structure, a definite margin of safety is required, and to arrive at a Design Stability Number, \( N_{ds} \), the Critical Stability Number, \( N_s \), must be reduced. The reduction of the Critical Stability Number was achieved by re-examining the model test results and noting the wave height which caused no damage to the foundation. This wave height was denoted \( H_{0.0} \) "No damage" was defined as follows:

a) When instability resulted from wash-out of the rubble from under the toe of the vertical superstructure (i.e. when \( d_1/d > 0.25 \) and with little or no penetration of the superstructure into the rubble mound), "no damage" was taken as the condition where not more than two pieces per foot rocked slightly at the toe of the vertical superstructure.
Fig. 12. Minimum design stability number, $N_s$, as a function of foundation depth, $d/L$, and relative depth, $d/L$. The design for rubble mound as a foundation. Design stability number, $N_s$, as a function of relative depth, $d/L$, and the foundation depth. $d/L$.
b) When instability resulted from erosion of the seaward slope of the rubble mound (i.e. (i) when \( \frac{d_l}{d} < 0.25 \) and with little or no penetration of the superstructure into the rubble mound, and (ii) for all values of \( \frac{d_l}{d} \) when the superstructure extended through the mound to the floor.) "No damage" was taken as the condition where not more than 1 per cent of the rubble units was displaced from the slope.

It must be emphasized that in effect there are two different stability criteria in use.

When \( H_{D=0} \) was determined for all cases, the Critical Stability Number \( N'_s \), was reduced by multiplying it by the ratio \( \frac{H_{D=0}}{H_{Crit}} \).

Thus, Design \( N_s = N'_s \frac{H_{D=0}}{H_{Crit}} \)  

In the test results for the case where the rubble mound was used primarily as a toe protection (Figure 10) it was not considered necessary to reduce the Stability Numbers for design purposes. ( \( H_{Crit} \) for this case was taken as the height causing 1% of the outer layer of rubble units to be displaced - a permissible amount of damage in the field.)

Figure 11 shows the variation of the Design Stability Number, \( N_s \), with \( d_l/L \) and \( d_t/d \), for zero penetration of the superstructure into the rubble mound.

Figure 12 is obtained from Figures 10 and 11 by noting the minimum values of \( N_s \) for each value of \( d_t/d \) and plotting this minimum \( N_s \) as a function of \( d_t/d \). Figure 12, then, presents the curves which are, at present, recommended for use in the design of rubble mound foundations and rubble mound toe protections for vertical breakwaters and seawalls.

Figure 12 has been used to calculate the curves shown in Figure 13 where the weight of rubble stone units required for given values of incident wave height, and selected values of specific weights of rock and water, may be obtained.

**Design Wave Heights:**

The proposed design curves of Figure 12 represent the relationship:

\[
N_s = \frac{\frac{g^{1/3} H_{D=0}}{W_r (S_r - 1)}}{g^{1/3}} = f(\frac{d_t}{d})
\]

(10)

The wave height in question is that which exists at the site of the structure and in the absence of the structure.
Most modern methods of wave forecasting give what has been termed the "significant wave", whose height is often denoted \( H_{\frac{1}{3}} \). (The significant wave height, \( H_{\frac{1}{3}} \), is defined as the average height of the highest one-third of waves.) Analysis of the statistical distribution of wave heights by Longuet-Higgins (1952) and Saville (1955) has shown that one wave in every hundred is likely to be 1.6 times the height of the significant wave, and that in a prolonged storm the maximum wave could be twice the height of the significant wave.

In the case of a composite breakwater with the superstructure resting directly on a rubble mound foundation, the safety of the whole structure and perhaps a whole harbour and the shipping in it, may depend on the ability of the foundation to resist the erosive effects of the highest waves.
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Therefore, for use of the test results given herein, in the design of such structures, it is at present suggested that the design wave height, \( H_{D,0} \), should be either

1. the maximum wave height measured at the vicinity of the site of the structure, if the duration of measurement is judged to be sufficiently long and accurate.

**OR**

2a. for important structures at very exposed sites where failure would be disastrous, and in the absence of factual records, the design wave height, \( H_{D,0} \), should be twice the value of the expected wave height at the structure based on \( H_{W_3} \) in deep water corrected for refraction and shoaling. (Breaking might preclude a wave of such magnitude and in such a case the greatest non-breaking wave should be taken for the design value of \( H_{D,0} \).)

2b. for less important structures where some risk of exceeding design conditions is acceptable, one and a half times the expected wave height.

**DISCUSSION OF RESULTS**

In the present series of tests the rubble mound was composed entirely of stones of approximately uniform size. In practice, a rubble mound foundation would be constructed with a core of dumped blast-run rock or quarry waste. The superstructure might consist of concrete or timber cribs which would be founded on the core of blast-run rock. An alternative method of constructing the superstructure would be to drive a pair of parallel tied-together walls of steel sheet piling into the rubble core. Finally, the apron and side-slopes of the core would be protected from erosion, by a cover layer of heavier, more uniformly sized, rock.

It is to the design of this cover layer that the tests described herein are intended to apply.

The practical prototype foundation is unlikely to correspond exactly to the conditions used in the present series of experiments. A situation where a superstructure, composed of steel sheet pile walls, is driven into the rubble core, corresponds most closely to the condition depicted in Figure 12 as "Rubble mound as toe protection". Other practical methods of construction are likely to fall somewhere between the two extreme conditions shown in Figure 12.

The outstanding points of uncertainty are, therefore, the effects of varying degrees of impermeability in the layers composing a prototype foundation, and the effects of varying amounts of penetration of the vertical superstructure into the rubble mound. Increased penetration of the superstructure certainly increases the overall stability and safety, and a relatively impermeable core is anticipated to produce similar results.
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In addition, the conditions at the pierhead, or seaward extremity of the structure, have not been investigated.

An analysis of prototype successes and failures in relation to the model test results would be invaluable in assessing the validity of the design curves proposed herein, and, if necessary, in their modification. Publication of data concerning such successes and failures would make this possible.

CONCLUSIONS

It is concluded from the results of model tests on the behaviour under wave action of a rubble mound foundation of a composite breakwater composed of rock of nearly uniform shape and size that:

a) the Stability Number, \( N_s = \frac{1/3H}{W_r (S_r-1)} \) is a useful and logical parameter for use in the study of the stability of rubble mounds under wave attack.

b) the Stability Number is primarily affected by the depth of the rubble mound foundation below the S.W.L. and by the relative depth \( (d/L) \) at the breakwater site.

c) since waves in nature have widely differing wave-lengths it is advisable to design the foundation on the basis of the minimum value of design Stability Number appropriate to the particular foundation depth \( (d_1/d) \).

d) increase in penetration of the superstructure into the rubble mound greatly increases the overall stability.

e) variation of the top width of the foundation mound on the seaward side, does not, for normal values of top width, appear to substantially affect the hydraulic aspects of the structure. In this respect, construction requirements and the dictates of Soil Mechanics will govern.

f) in the case of natural wave trains, the selection of the design wave height requires a decision on the part of the designer as to the acceptable risk of exceeding design conditions.

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REFERENCES


APPENDIX - NOTATION

LIST OF SYMBOLS AS USED IN THIS PAPER

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<th>Symbol</th>
<th>Definition</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>B</td>
<td>Top width, on seaward side, of foundation mound.</td>
<td>ft.</td>
</tr>
<tr>
<td>C_D</td>
<td>A drag coefficient.</td>
<td></td>
</tr>
<tr>
<td>C_M</td>
<td>An inertia coefficient.</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td>Depth of Still Water measured from the bottom normal to that Still Water surface; also, the depth of water in the vicinity of a structure.</td>
<td>ft.</td>
</tr>
</tbody>
</table>
COASTAL ENGINEERING

\(d_i\) : Depth of top of foundation mound below the Still Water Level. ft.

\(d/L\) : Relative Depth: ratio of still water depth of wave length.

\(D\) : A characteristic linear dimension of a rubble unit; the diameter of a sphere having an equal volume. ft.

\(\overline{D}\) : A subscript referring to a drag force.

\(f\) : "a function of"

\(g\) : Gravitational acceleration (= 32.2 ft/sec\(^2\)). ft/sec\(^2\)

\(H\) : Wave height; amplitude; height of incident wave. ft.

\(H_{D=0}\) : Incident wave height causing "no-damage" to structure. ft.

\(H_{crit}\) : Critical wave height: Incident wave height at condition of limiting equilibrium of structure. ft.

\(\overline{H}\) : A subscript referring to the horizontal direction.

\(H/L\) : Wave steepness: ratio of wave height to wave length.

\(\overline{I}\) : A subscript referring to inertia force.

\(k\) : = \(2\pi/T\)

\(L\) : Wave length. ft.

\(m\) : = \(2\pi/L\)

\(\overline{max}\) : A subscript referring to the maximum value.

\(N_s\) : A Stability Number for rubble mounds.

\[N_s = \frac{\gamma_r^{1/3} H}{W_r^{1/3}(S_r - 1)}\]

\(N'_s\) : Critical Stability Number: Stability number at condition of limiting equilibrium -

\[N'_s = \frac{\gamma_r^{1/3} H_{crit}}{W_r^{1/3}(S_r - 1)}\]

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LABORATORY STUDY OF RUBBLE FOUNDATIONS
FOR VERTICAL BREAKWATERS

$S_r$ : Specific Gravity of rubble or armour stone.

\[ S_r = \frac{\gamma_r}{\gamma_w} \]

S.W.L : Still Water Level.

$t$ : A time. \hspace{2cm} \text{secs.}

$T$ : Wave period. \hspace{2cm} \text{secs.}

$u$ : Horizontal component of orbital velocity. \hspace{2cm} \text{ft/sec}

$v$ : Vertical component of orbital velocity. \hspace{2cm} \text{ft/sec}

$V$ : A velocity. \hspace{2cm} \text{ft/sec}

$-\nu$ : A subscript referring to the vertical direction.

$W_r$ : Weight of individual unit of rubble mound foundation \hspace{2cm} \text{lbs.}

(actualy the mean weight of a unit in a "nearly one-size" rubble mound.)

$x$ : A horizontal distance from the origin of coordinates. \hspace{2cm} \text{ft.}

$y$ : Depth below Still Water Level. (negative downwards) \hspace{2cm} \text{ft.}

$\alpha$ : Angle of a rubble mound (or breakwater) slope \hspace{2cm} \text{degrees}

measured from the horizontal.

$\beta$ : A coefficient stating the proportionality of the \hspace{2cm} 

weight of a rubble unit to its volume.

$\gamma_t$ : Unit weight of the water in which the structure is \hspace{2cm} \text{lbs/cu.ft.}

located.

\[ \gamma_r = 62.4 \text{ lbs/cu.ft. for fresh water} \]

\[ \gamma_s = 64.0 \text{ lbs/cu.ft. for salt water} \]

$\gamma_r$ : Unit weight of rock (rubble). \hspace{2cm} \text{lbs/cu.ft.}

$\Delta$ : Denotes the shape of the rubble or armour units.

$\mu$ : A friction coefficient.

$\sigma_1, \sigma_2$ : Constants.

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