Sub-grid modeling of coupled hydrodynamic, vegetative and morphodynamic processes in a salt marsh environment Mithun Deb¹ James T. Kirby¹ Ali Abdolali² Fengyan Shi¹ ¹ Center for Applied Coastal Research, University of Delaware

2 National Oceanic and Atmospheric Administration



36TH INTERNATIONAL CONFERENCE ON COASTAL ENGINEERING 2018

Baltimore, Maryland | July 30 - August 3, 2018

The State of the Art and Science of Coastal Engineering



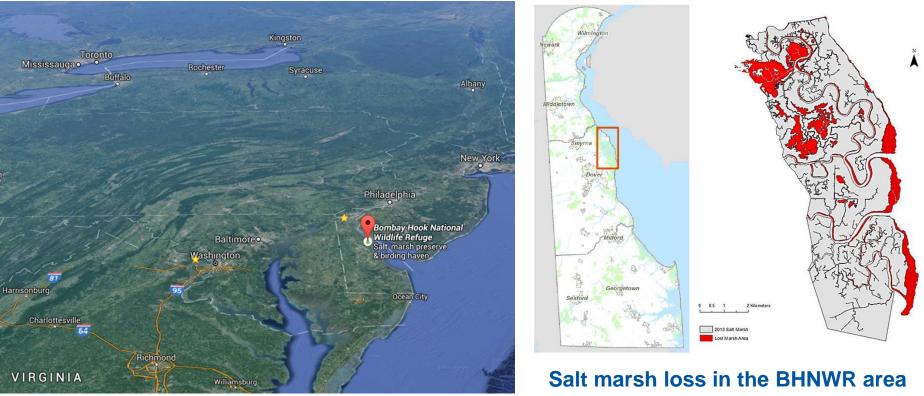








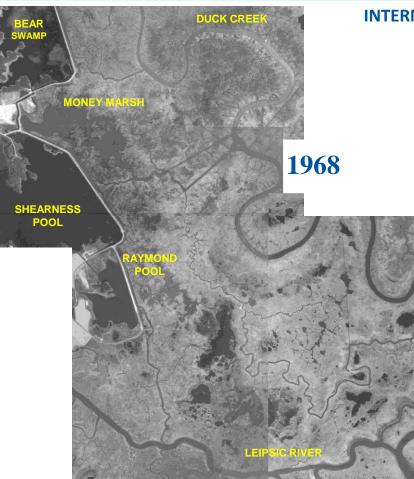
Motivations



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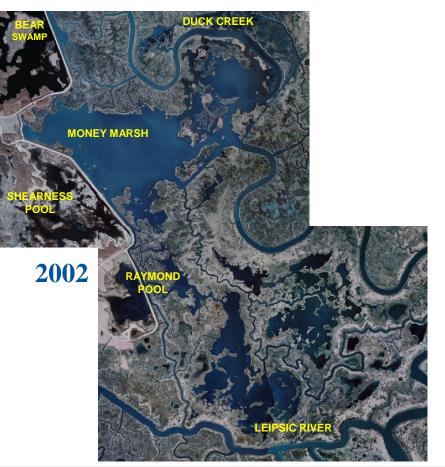
[figure: McDowell and Sommerfield (2016)]

Motivations



INTERNAL MARSH LOSS AT BOMBAY HOOK NWR

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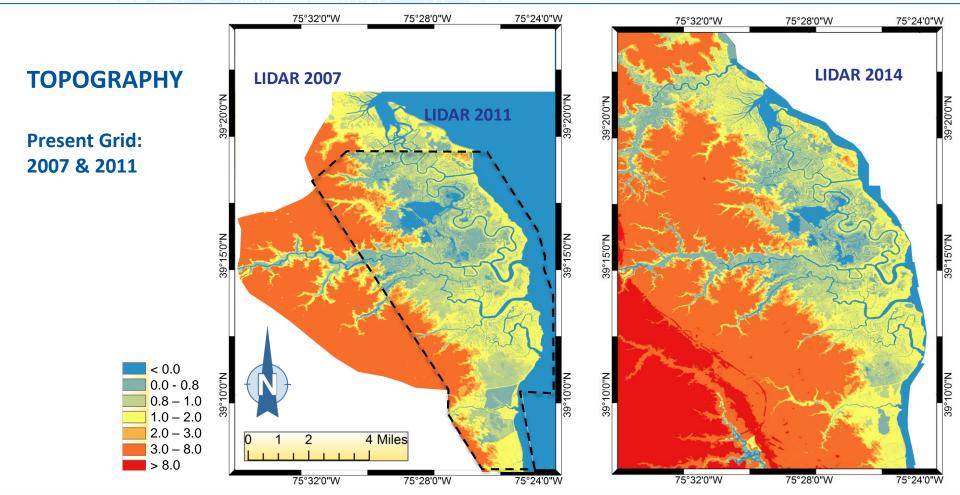


Conduct a comprehensive numerical and field investigation to understand:

- The dominant hydrodynamics for present marsh conditions
- Wave climate in the tidally-inundated flat and long term potential for wind wave-driven shoreline erosion
- Net sediment transport (importing/exporting)
- Coupled hydrodynamic, vegetative and morphodynamic processes

A significant hydrodynamic modeling limitation: artificial ponding over the marsh platforms

DEM development



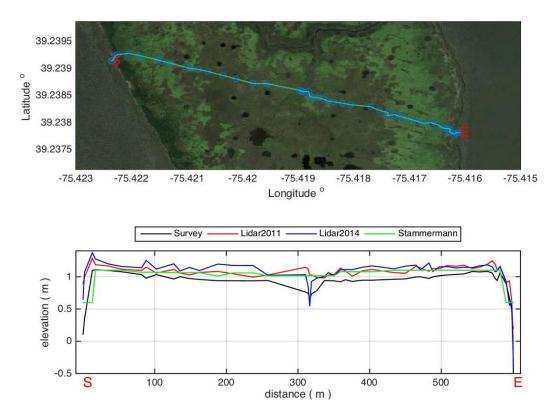
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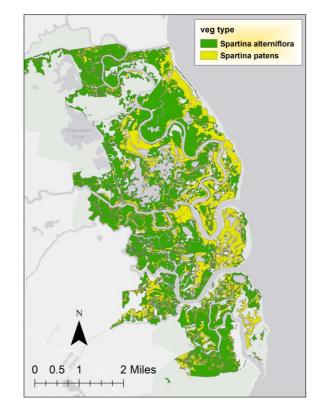
DEM development

LIDAR Comparison

1300 points collected during a ground truth survey

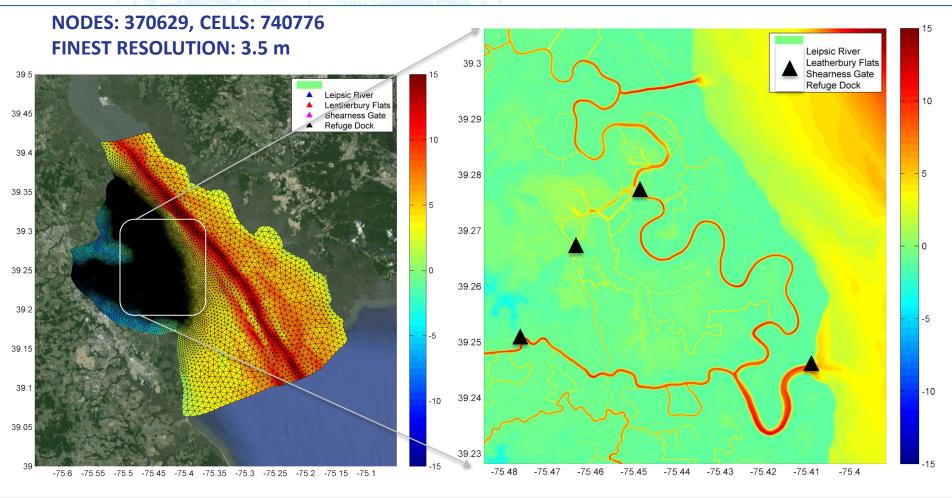
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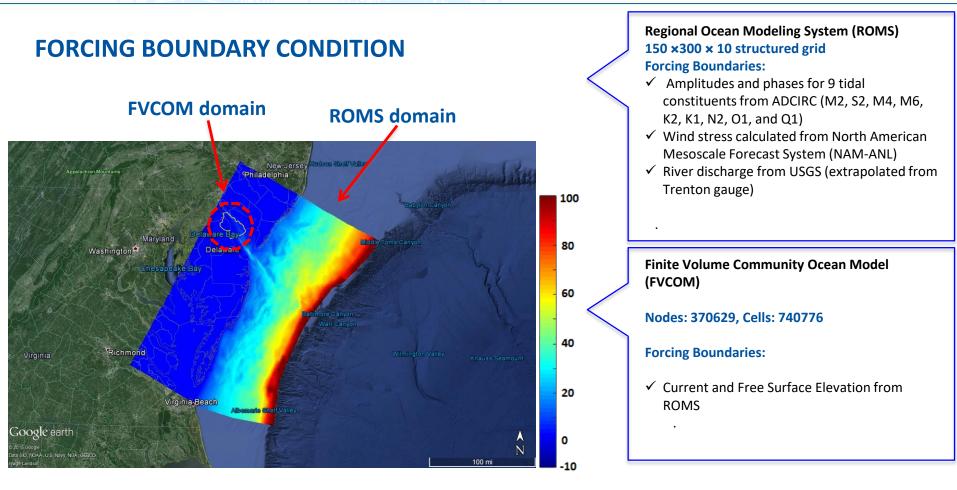
vegetation bias correction

Unstructured Grid



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Hydrodynamic Models



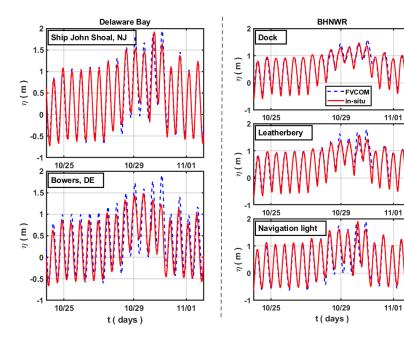
Model validation

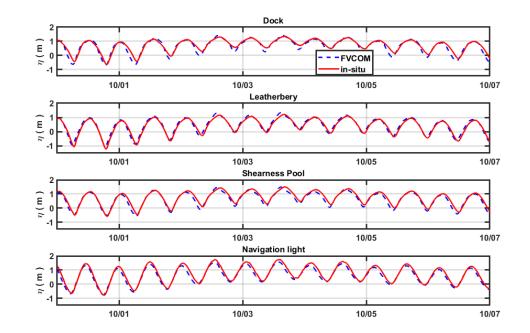


FVCOM model comparison (at Bay and channel tide gauges)

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WARE





During September storm, 2015

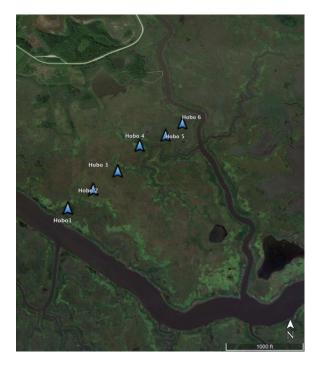
During Hurricane Sandy, 2012

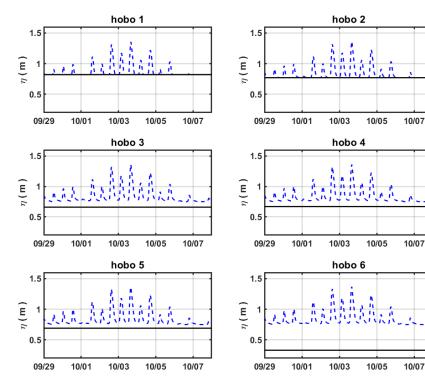
Model validation



surface elevation

FVCOM model comparison (at marsh platform)



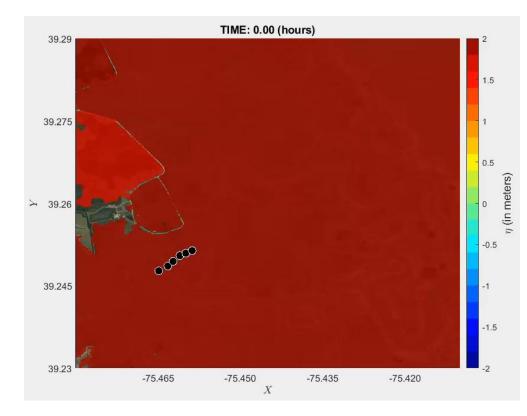


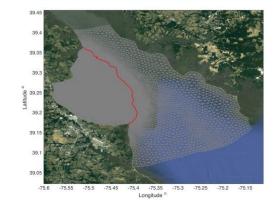
During September storm, 2015

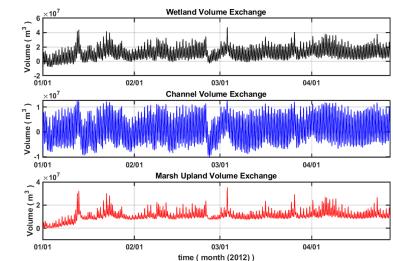
Model grid elevation (black straight line)

Total volume of water going in and out of BHNWR

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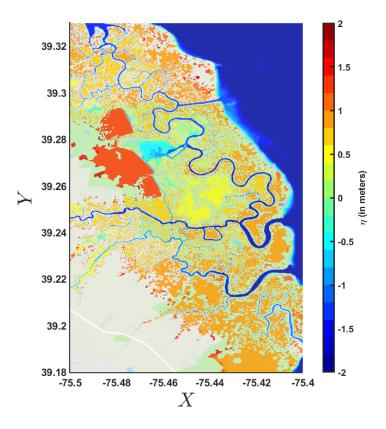




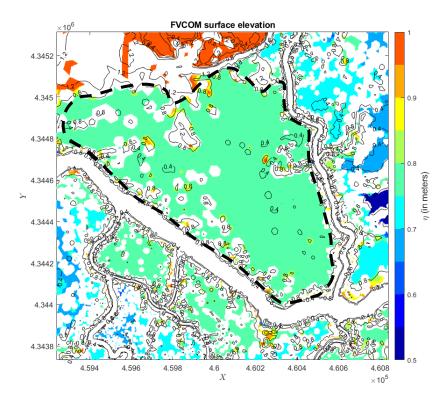


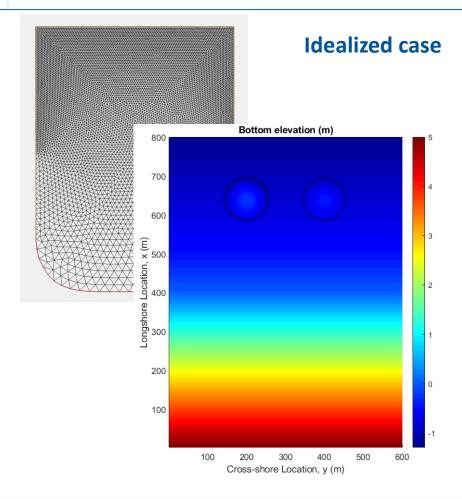
Ongoing work

 Treatment of artificial ponding over marsh platforms



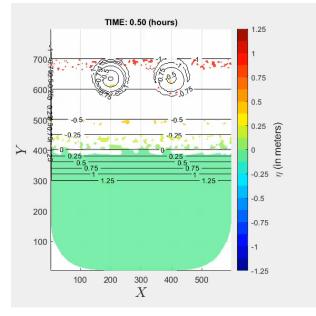
Identifying the marsh depressions





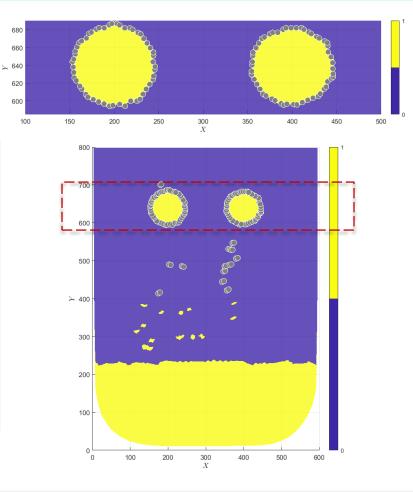
Identifying the marsh depressions

surface elevation



wet/dry mask

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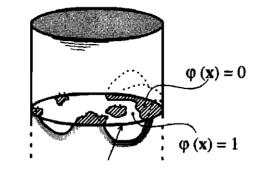


Development of Sub-grid Equations

• Defina (2000): Volume averaging

$$\begin{split} \Theta \frac{\partial \eta}{\partial t} + \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} &= 0 \\ \frac{\partial P}{\partial t} + \frac{\partial}{\partial x} \left(\epsilon_{xx} \frac{P^2}{Y} \right) + \frac{\partial}{\partial y} \left(\epsilon_{xy} \frac{PQ}{Y} \right) + gY \frac{\partial \eta}{\partial x} - \frac{\partial R_{xx}}{\partial x} - \frac{\partial R_{xy}}{\partial y} - \frac{\tau_{sx}}{\rho} + \frac{\tau_{bx}}{\rho} &= 0 \\ \frac{\partial Q}{\partial t} + \frac{\partial}{\partial x} \left(\epsilon_{xy} \frac{PQ}{Y} \right) + \frac{\partial}{\partial y} \left(\epsilon_{yy} \frac{Q^2}{Y} \right) + gY \frac{\partial \eta}{\partial y} - \frac{\partial R_{yx}}{\partial x} - \frac{\partial R_{yy}}{\partial y} - \frac{\tau_{sy}}{\rho} + \frac{\tau_{by}}{\rho} &= 0 \\ \end{split}$$

$$\begin{split} \textbf{Porosity}: \qquad \textbf{Effective water depth}: \\ \Theta &= \frac{1}{A} \iint_{A} \varphi|_{z=\eta} dA \qquad Y = \frac{1}{A} \int_{-h}^{\eta} \iint_{A} \varphi dA dz \end{split}$$

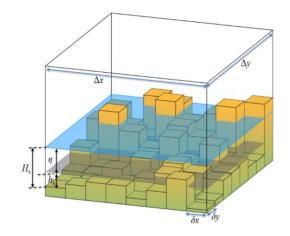


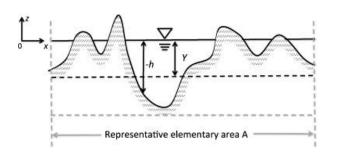
- 2-D equations that solves partially wet elements
- Stochastic representation of porosity parameter for the Venice lagoon

Development of Sub-grid Equations

Deterministic case

- Volp et al. (2013): Treatment of friction slope
 - Unidirectional flow within a coarse grid cell
 - Uniform friction slope in a coarse grid cell
- Wu et al. (2016): Pre-storage of volume averages





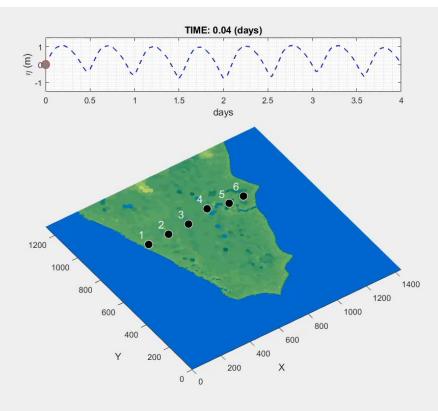
Porosity :Effective water depth :
$$\Theta = \frac{1}{A} \iint_{A} \varphi|_{z=\eta} dA$$
 $Y = \frac{1}{A} \int_{-h}^{\eta} \iint_{A} \varphi dA dz$

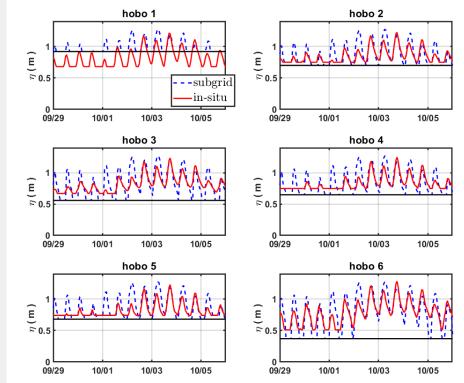
$$\varphi(\mathbf{x}) = \begin{cases} 1 & z > -h \\ 0 & z \le -h \end{cases}$$

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Sub-grid simulation at Hobo gauge locations (Stochastic case)

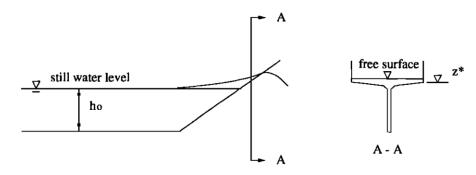
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Slot method in FVCOM (future work)

• Kennedy et al. (2000), Chen et al. (2000)



elevation at the top of the slot

$$z^* = \frac{-h}{1-\delta} + h_0 \left(\frac{\delta}{1-\delta} + \frac{1}{\lambda}\right)$$

width of the plume

$$b(\eta) = \begin{cases} 1, & \eta \ge z^* \\ \delta + (1 - \delta)e^{\lambda(\eta - z^*)/h_0}, & \eta \le z^* \end{cases}$$

$$\beta \eta_{t} + \nabla \cdot \mathbf{M} = 0$$
where
$$\mathbf{M} = \Lambda \left[\mathbf{u}_{\alpha} + \left(\frac{z_{\alpha}^{2}}{2} - \frac{1}{6} \left(h^{2} - h \eta + \eta^{2} \right) \right) \nabla (\nabla \cdot \mathbf{u}_{\alpha}) + \left(z_{\alpha} + \frac{1}{2} \left(h - \eta \right) \right) \nabla (\nabla \cdot (h \mathbf{u}_{\alpha})) \right]$$



Ongoing work

- Improvement of the FVCOM model with narrow slot approach
- Implementing the subgrid model with vegetation and morphodynamic module for long-term morphology changes

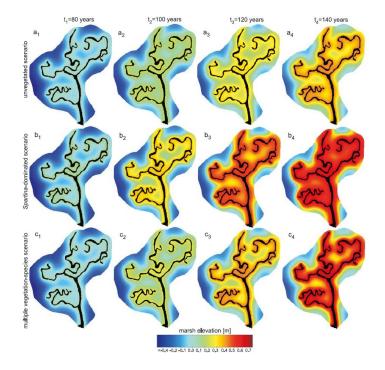
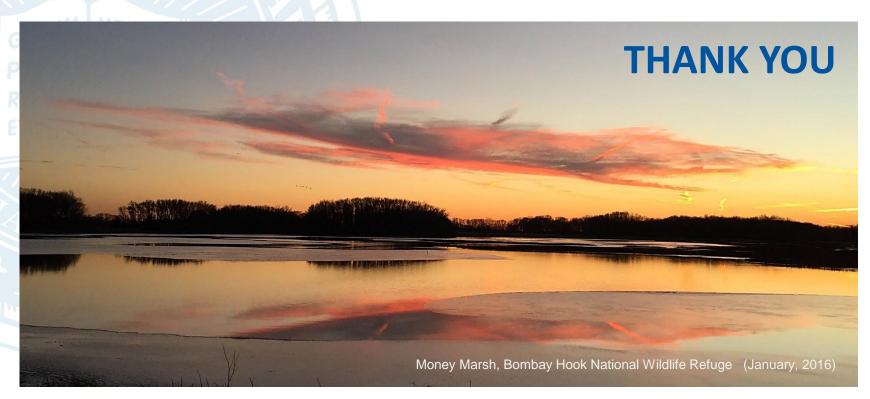


figure from D'Alpaos et al. (2007)













Supplemental info

References

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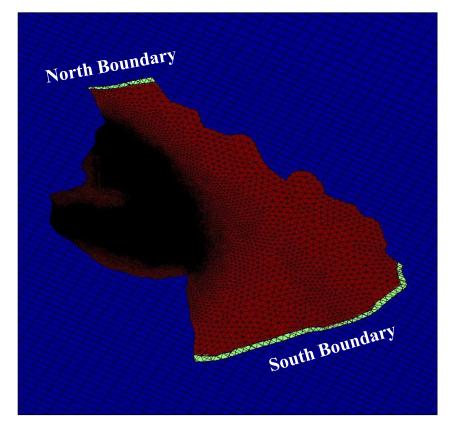
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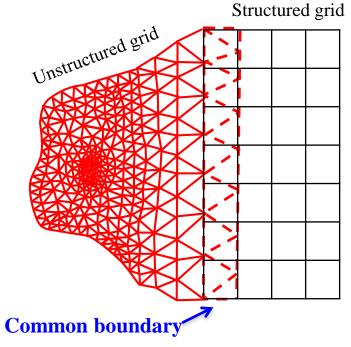
Hydrodynamic Models

Forcing boundary condition



Direct Nesting

VARF



Velocity: Coarse grid vs. Subgrid

Assumptions : within a coarse grid

Unidirectional flow

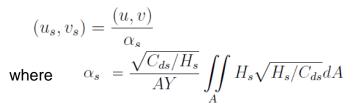
Δx

2. Constant friction slope

Velocity at coarse grid :

$$u = \frac{1}{AY} \iint_{A} H_s u_s dA$$

Relation between velocities at coarse grid and subgrid



Pre-storage Method

Lookup tables for

Porosity at surface

$$\Theta = \frac{1}{A} \iint_A \varphi|_{z=\eta} dA$$

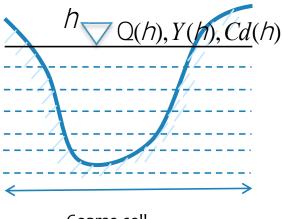
Effective water depth

$$Y = \frac{1}{A} \int_{-h}^{\eta} \iint_{A} \varphi dA dz$$

Equivalent friction coefficient

$$C_d = \frac{1}{A} \iint_A \frac{H_s}{H_f} dA$$

Q(h), Y(h), Cd(h) are obtained by linear interpolation or polynomial fitting method



Coarse cell

Subgrid Sediment Model

Sediment Module

$$Y\frac{\partial \bar{c}}{\partial t} + \Theta \bar{c}\frac{\partial \eta}{\partial t} + \frac{\partial \bar{c}P}{\partial x} + \frac{\partial \bar{c}Q}{\partial y} - \left[\frac{\partial}{\partial x}\left(\nu Y\frac{\partial \bar{c}}{\partial x}\right) + \frac{\partial}{\partial y}\left(\nu Y\frac{\partial \bar{c}}{\partial y}\right)\right] - S = 0$$

$$S = E - D = \iint_{A_{vet}} E_s dA - \iint_{A_{vet}} (D_s + D_p) dA$$

$$E_s = \begin{cases} M\left(\frac{\tau_s}{\tau_{ce}} - 1\right) & \tau_s > \tau_{ce} \\ 0 & \tau_s \le \tau_{ce} \end{cases} D_s = \begin{cases} \omega_s c_s \left(1 - \frac{\tau_s}{\tau_{cd}}\right) & \tau_s < \tau_{ce} \\ 0 & \tau_s \ge \tau_{cd} \end{cases} C_s = \alpha_\epsilon \left(\frac{Ud_s}{\nu}\right)^{\beta_\epsilon} \left(\frac{d_{50}}{d_s}\right)^{\gamma_\epsilon} \end{cases}$$

$$\rho_b \frac{\partial Z_b}{\partial t} + \frac{f_{\text{mor}}}{1 - p_b} \left(E - D - D_{bg} \right) = 0$$

Organic deposition: $D_{bg} = D_{bg,0} \frac{B}{B_{max}}$

Friction: Coarse grid vs. sub-grid

Total bottom friction

$$\tau_{\mathbf{b}} = \frac{\rho}{A} \iint_{A} C_{ds} |\mathbf{u}_{\mathbf{s}}| \mathbf{u}_{\mathbf{s}} dA, \quad \text{with} |\mathbf{u}_{\mathbf{s}}| = \sqrt{u_s^2 + v_s^2}$$
$$\tau_{bx} = \frac{\rho u |\mathbf{u}|}{A} \iint_{A} \frac{C_{ds}}{\alpha_s^2} dA$$
$$= \rho C_d u |\mathbf{u}|$$

Effective friction coefficient C_d , frictional depth H_f

